

Università degli Studi Roma Tre - Corso di Laurea in Matematica

Tutorato di Analisi 3

A.A. 2009-2010 - Docente: Prof. P. Esposito

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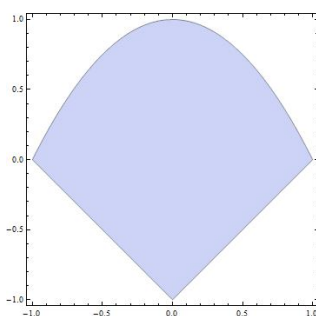
SOLUZIONI DEL TUTORATO NUMERO 9 (10/12 MAGGIO 2010)

INTEGRALI CON FUBINI E CON CAMBIO DI VARIBILE

I testi e le soluzioni dei tutorati sono disponibili al seguente indirizzo:

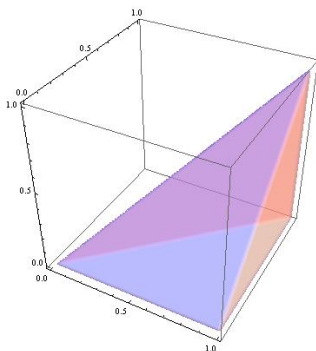
<http://www.lifedreamers.it/liuck>

1. $A = \{(x, y) \in \mathbb{R}^2 : |x| - 1 \leq y \leq 1 - x^2\} = \{(x, y) \in \mathbb{R}^2 : -1 \leq x \leq 1, |x| - 1 \leq y \leq 1 - x^2\}.$



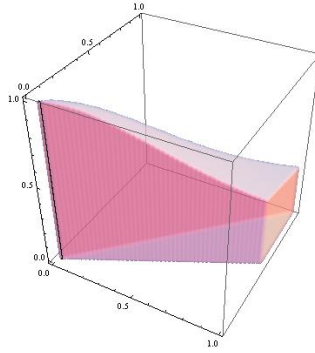
$$\begin{aligned} \int_A |x| \cos(\pi y) dx dy &= \int_{-1}^1 |x| dx \int_{|x|-1}^{1-x^2} \cos(\pi y) dy = \int_{-1}^1 |x| dx \left[\frac{\sin(\pi y)}{\pi} \right]_{|x|-1}^{1-x^2} = \\ &= \frac{1}{\pi} \int_{-1}^1 |x| dx (\sin(\pi(1-x^2)) - \sin(\pi(|x|-1))) = \frac{2}{\pi} \int_0^1 x (\sin(\pi(1-x^2)) - \\ &- \sin(\pi(x-1))) dx = \frac{2}{\pi} \int_0^1 x \sin(\pi(1-x^2)) dx - \frac{2}{\pi} \int_0^1 x \sin(\pi(x-1)) dx \stackrel{t=\pi(x^2-1)}{=} \\ &= \frac{2}{\pi} \int_{-\pi}^0 \frac{\sin(-t)}{2\pi} dt - \frac{2}{\pi} \left(\left[\frac{-x \cos(\pi(x-1))}{\pi} \right]_0^1 + \int_0^1 \frac{\cos(\pi(x-1))}{\pi} dx \right) = \\ &= \frac{2}{\pi} \left[\frac{\cos(-t)}{2\pi} \right]_{-\pi}^0 - \frac{2}{\pi} \left(-\frac{1}{\pi} + \left[\frac{\sin(\pi(x-1))}{\pi^2} \right]_0^1 \right) = \frac{2}{\pi^2} - \frac{2}{\pi} \left(-\frac{1}{\pi} \right) = \frac{4}{\pi^2}. \end{aligned}$$

2. $B = \{(x, y, z) \in \mathbb{R}^3 : 0 \leq x \leq 1, 0 \leq y \leq x, 0 \leq z \leq y\}.$



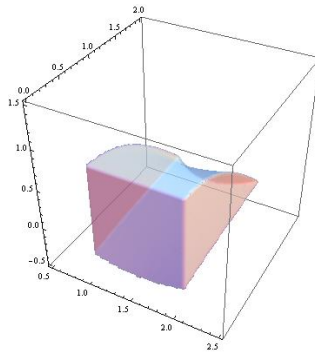
$$\begin{aligned}
\int_B x^4 y^2 e^{xyz} dx dy dz &= \int_0^1 x^4 dx \int_0^x y^2 dy \int_0^y e^{xyz} dz = \int_0^1 x^4 dx \int_0^x y^2 dy \left[\frac{e^{xyz}}{xy} \right]_0^y = \\
&= \int_0^1 x^3 dx \int_0^x y (e^{xy^2} - 1) dy = \int_0^1 x^3 dx \left[\frac{e^{xy^2}}{2x} - \frac{y^2}{2} \right]_0^x = \int_0^1 x^3 \left(\frac{e^{x^3}}{2x} - \frac{x^2}{2} - \frac{1}{2} \right) dx = \\
&= \int_0^1 \left(\frac{x^2 e^{x^3}}{2} - \frac{x^5}{2} - \frac{x^2}{2} \right) dx = \left[\frac{e^{x^3}}{6} - \frac{x^6}{12} - \frac{x^3}{6} \right]_0^1 = \frac{e}{6} - \frac{1}{12} - \frac{1}{6} - \frac{1}{6} = \frac{e}{6} - \frac{5}{12}.
\end{aligned}$$

$$\begin{aligned}
3. C &= \left\{ (x, y, z) \in \mathbb{R}^3 : x \leq 2y \leq 2x \leq 2, 0 \leq x^2 z + y^2 z + z \leq 1 \right\} = \\
&= \left\{ (x, y, z) \in \mathbb{R}^3 : 0 \leq x \leq 1, \frac{x}{2} \leq y \leq x, 0 \leq z \leq \frac{1}{x^2 + y^2 + 1} \right\}
\end{aligned}$$



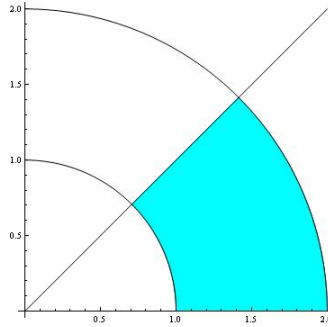
$$\begin{aligned}
\int_C (x^2 + y^2 + 1) \arctan x dx dy dz &= \int_0^1 \arctan x dx \int_{\frac{x}{2}}^x (x^2 + y^2 + 1) dy \int_0^{\frac{1}{x^2 + y^2 + 1}} dz = \\
&= \int_0^1 \arctan x dx \int_{\frac{x}{2}}^x (x^2 + y^2 + 1) \frac{1}{x^2 + y^2 + 1} dy = \int_0^1 \arctan x [y]_{\frac{x}{2}}^x = \int_0^1 \frac{x \arctan x}{2} dx = \\
&= \left[\frac{x^2 \arctan x}{4} \right]_0^1 - \int_0^1 \frac{x^2}{4(x^2 + 1)} dx = \frac{\pi}{16} + \frac{1}{4} \int_0^1 \left(\frac{1}{x^2 + 1} - 1 \right) dx = \frac{\pi}{16} + \frac{1}{4} [\arctan x - x]_0^1 = \\
&= \frac{\pi}{16} + \frac{\pi}{16} - \frac{1}{4} = \frac{\pi}{8} - \frac{1}{4}.
\end{aligned}$$

$$\begin{aligned}
4. D &= \left\{ (x, y, z) \in \mathbb{R}^3 : -\frac{\sin^3 x + \sin^4 x}{(\pi + 2y)^2} \leq z \leq \cos(y \sin x), 0 \leq y \sin x \leq \frac{\pi}{2}, \frac{\pi}{3} \leq x \leq \frac{2}{3}\pi \right\} = \\
&= \left\{ (x, y, z) \in \mathbb{R}^3 : -\frac{\sin^3 x + \sin^4 x}{(\pi + 2y)^2} \leq z \leq \cos(y \sin x), 0 \leq y \leq \frac{\pi}{2 \sin x}, \frac{\pi}{3} \leq x \leq \frac{2}{3}\pi \right\}
\end{aligned}$$



$$\begin{aligned}
Vol(D) &= \int_{\frac{\pi}{3}}^{\frac{2}{3}\pi} dx \int_0^{\frac{\pi}{2\sin x}} dy \int_{-\frac{\sin^3 x + \sin^4 x}{(\pi+2y)^2}}^{\cos(y \sin x)} dz = \int_{\frac{\pi}{3}}^{\frac{2}{3}\pi} dx \int_0^{\frac{\pi}{2\sin x}} \left(\cos(y \sin x) + \frac{\sin^3 x + \sin^4 x}{(\pi+2y)^2} \right) dy = \\
&= \int_{\frac{\pi}{3}}^{\frac{2}{3}\pi} dx \left[\frac{\sin(y \sin x)}{\sin x} - \frac{\sin^3 x + \sin^4 x}{2(\pi+2y)} \right]_0^{\frac{\pi}{2\sin x}} = \int_{\frac{\pi}{3}}^{\frac{2}{3}\pi} \left(\frac{1}{\sin x} - \frac{\sin^3 x + \sin^4 x}{2\pi + \frac{2\pi}{\sin x}} + \frac{\sin^3 x + \sin^4 x}{2\pi} \right) dx = \\
&= \int_{\frac{\pi}{3}}^{\frac{2}{3}\pi} \left(\frac{1}{\sin x} - \frac{\sin^4 x}{2\pi} + \frac{\sin^3 x + \sin^4 x}{2\pi} \right) dx = \int_{\frac{\pi}{3}}^{\frac{2}{3}\pi} \left(\frac{1}{\sin x} + \frac{\sin^3 x}{2\pi} \right) dx = \\
&= \int_{\frac{\pi}{3}}^{\frac{2}{3}\pi} \left(\frac{\sin x}{1 - \cos^2 x} + \frac{\sin x (1 - \cos^2 x)}{2\pi} \right) dx \stackrel{t=\cos x}{=} - \int_{\frac{1}{2}}^{-\frac{1}{2}} \left(\frac{1}{1-t^2} + \frac{1-t^2}{2\pi} \right) dt = \\
&= \int_{-\frac{1}{2}}^{\frac{1}{2}} \left(\frac{1}{2(1+t)} + \frac{1}{2(1-t)} + \frac{1}{2\pi} - \frac{t^2}{2\pi} \right) dt = \left[\frac{\log(1+t)}{2} - \frac{\log(1-t)}{2} + \frac{t}{2\pi} - \frac{t^3}{6\pi} \right]_{-\frac{1}{2}}^{\frac{1}{2}} = \\
&= \frac{\log\left(\frac{3}{2}\right)}{2} - \frac{\log\left(\frac{1}{2}\right)}{2} + \frac{1}{4\pi} - \frac{1}{48\pi} - \frac{\log\left(\frac{1}{2}\right)}{2} + \frac{\log\left(\frac{3}{2}\right)}{2} + \frac{1}{4\pi} - \frac{1}{48\pi} = \log\left(\frac{3}{2}\right) - \log\left(\frac{1}{2}\right) + \frac{11}{24}\pi = \\
&= \log 3 + \frac{11}{24}\pi.
\end{aligned}$$

5. $A = \{(x, y) \in \mathbb{R}^2 : 0 \leq y \leq x, 1 \leq x^2 + y^2 \leq 4\}$ $f(x, y) = \frac{y}{x}$
Passiamo in coordinate polari cioè poniamo $(x, y) = \Phi(\rho, \theta) = (\rho \cos \theta, \rho \sin \theta)$.



Notiamo che $\Phi^{-1}(A) = \{(\rho, \theta) \in \mathbb{R}^2 : 1 \leq \rho \leq 2, \theta \leq \frac{\pi}{4}\}$ e che la matrice Jacobiana di Φ è $J\Phi(\rho, \theta) = \begin{pmatrix} \cos \theta & -\rho \sin \theta \\ \sin \theta & \rho \cos \theta \end{pmatrix} \implies |\det J\Phi| = \rho$.

Per la formula del cambio di variabile abbiamo quindi che

$$\begin{aligned}
\int_A f(x, y) dx dy &= \int_{\Phi^{-1}(A)} f(\Phi(\rho, \theta)) \rho d\rho d\theta = \int_{\Phi^{-1}(A)} \frac{\rho \sin \theta}{\rho \cos \theta} \rho d\rho d\theta = \int_{\Phi^{-1}(A)} \rho \tan \theta d\rho d\theta = \\
&= \int_1^2 d\rho \int_0^{\frac{\pi}{4}} d\theta \rho \tan \theta = \int_1^2 d\rho \rho \int_0^{\frac{\pi}{4}} d\theta \tan \theta = \int_1^2 d\rho \rho (-\log \cos \theta) \Big|_0^{\frac{\pi}{4}} = \frac{1}{2} \log 2 \int_1^2 \rho d\rho = \\
&= \frac{1}{2} \log 2 \frac{1}{2} \rho^2 \Big|_1^2 = \frac{1}{4} \log 2 (4 - 1) = \frac{3}{4} \log 2.
\end{aligned}$$

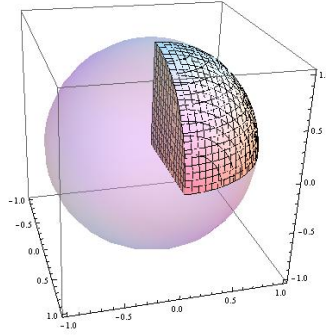
6. $B = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 1, x, y, z \geq 0\}$ $f(x, y, z) = \frac{x^2}{4 - x^2 - y^2 - z^2}$

Passiamo in coordinate sferiche cioè poniamo

$$(x, y, z) = \Phi(\rho, \theta, \varphi) = (\rho \cos \theta \sin \varphi, \rho \sin \theta \sin \varphi, \rho \cos \varphi).$$

Notiamo che $\Phi^{-1}(B) = \{(\rho, \theta, \varphi) \in \mathbb{R}^3 : 0 \leq \rho \leq 1, 0 \leq \theta \leq \frac{\pi}{2}, 0 \leq \varphi \leq \frac{\pi}{2}\}$ e che la ma-

$$\text{trice Jacobiana di } \Phi \text{ è } J\varphi(\rho, \theta, \varphi) = \begin{pmatrix} \cos \theta \sin \varphi & -\rho \sin \theta \sin \varphi & \rho \cos \theta \cos \varphi \\ \sin \theta \sin \varphi & \rho \cos \theta \sin \varphi & \rho \sin \theta \cos \varphi \\ \cos \varphi & 0 & -\rho \sin \varphi \end{pmatrix} \implies$$

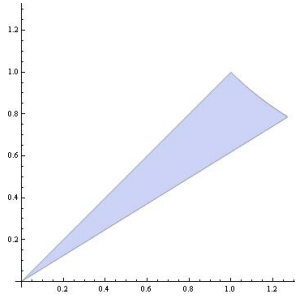


$$|\det J\Phi| = \rho^2 \sin \varphi.$$

Per la formula del cambio di variabile abbiamo quindi che

$$\begin{aligned} \int_B f(x, y, z) \, dx dy dz &= \int_{\Phi^{-1}(B)} f(\Phi(\rho, \theta, \varphi)) \rho^2 \sin \varphi \, d\rho d\theta d\varphi = \int_0^1 d\rho \int_0^{\frac{\pi}{2}} d\theta \int_0^{\frac{\pi}{2}} d\varphi \frac{\rho^4 \cos^2 \theta \sin \varphi}{4 - \rho^2} \\ &= \int_0^1 d\rho \frac{\rho^4}{4 - \rho^2} \int_0^{\frac{\pi}{2}} d\theta \cos^2 \theta \int_0^{\frac{\pi}{2}} d\varphi \sin \varphi = \int_0^1 d\rho \frac{\rho^4}{4 - \rho^2} \int_0^{\frac{\pi}{2}} d\theta \cos^2 \theta (-\cos \varphi) \Big|_0^{\frac{\pi}{2}} = \\ &= \int_0^1 d\rho \frac{\rho^4}{4 - \rho^2} \int_0^{\frac{\pi}{2}} d\theta \cos^2 \theta = \frac{\pi}{4} \int_0^1 d\rho \frac{\rho^4}{4 - \rho^2} d\rho = \frac{\pi}{4} \int_0^1 \left(-4 - \rho^4 + \frac{4}{2 - \rho} + \frac{4}{2 + \rho} \right) d\rho = \\ &= \frac{\pi}{2} \left[-4\rho - \frac{\rho^5}{5} - 4 \log(2 - \rho) + 4 \log(2 + \rho) \right]_0^1 = \frac{\pi}{4} \left(4 \log 3 - \frac{13}{3} \right) = \pi \left(\log 3 - \frac{13}{12} \right) \end{aligned}$$

7. $C = \{(x, y) \in \mathbb{R}^2 : 0 \leq x^2 - y^2 \leq xy \leq 1, x \geq 0\}$ $f(x, y) = (x^4 - y^4)e^{xy}$



Poniamo $u = x^2 - y^2$ e $v = xy$ cioè $(u, v) = G(x, y) = (x^2 - y^2, xy)$.

$$G(C) = \{(u, v) \in \mathbb{R}^2 : 0 \leq u \leq v \leq 1\} = \{(u, v) \in \mathbb{R}^2 : 0 \leq u \leq 1, u \leq v \leq 1\}.$$

Notiamo che se $(x, y) \in C$ allora $\begin{cases} u = x^2 - y^2 \\ v = xy \end{cases} \implies u^2 + 4v^2 = (x^2 + y^2)^2 \implies x^2 + y^2 =$

$$\sqrt{u^2 + 4v^2} \text{ da cui ricaviamo che } \begin{cases} \sqrt{u^2 + 4v^2} + u = 2x^2 \\ \sqrt{u^2 + 4v^2} - u = 2y^2 \end{cases} \implies \begin{cases} x = \sqrt{\frac{1}{2}(\sqrt{u^2 + 4v^2} + u)} \\ y = \sqrt{\frac{1}{2}(\sqrt{u^2 + 4v^2} - u)} \end{cases}$$

Questo ci dice che G è una applicazione biettiva tra G e $G(B)$ e che $G^{-1}(u, v) =$

$$\Phi(u, v) = \left(\sqrt{\frac{1}{2}(\sqrt{u^2 + 4v^2} + u)}, \sqrt{\frac{1}{2}(\sqrt{u^2 + 4v^2} - u)} \right). \text{ Il cambio di variabili } (u, v) =$$

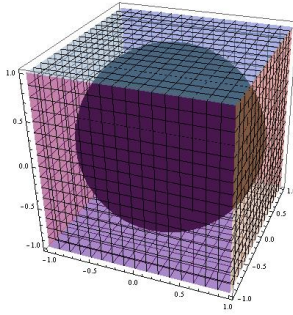
$\Phi(x, y)$ è equivalente a $(x, y) = \Phi(u, v)$. Inoltre $\Phi^{-1}(C) = G(C)$ e $\det JG(x, y) =$

$$\det \begin{pmatrix} 2x & -2y \\ y & x \end{pmatrix} = 2(x^2 + y^2) \text{ quindi } \det J\Phi(u, v) = \frac{1}{2(x^2 + y^2)} \Big|_{(x, y) = \Phi(u, v)}.$$

Per il teorema del cambio di variabile abbiamo quindi che

$$\begin{aligned} \int_C f(x, y) dx dy &= \int_{\Phi^{-1}(C)} f(\Phi(x, y)) \frac{1}{2(x^2 + y^2)} \Big|_{(x, y) = \Phi(u, v)} dudv = \frac{1}{2} \int_{\Phi^{-1}(C)} (x^2 - y^2) e^{xy} \Big|_{(x, y) = \Phi(u, v)} dudv = \\ &= \frac{1}{2} \int_{\Phi^{-1}(C)} ue^v dudv = \frac{1}{2} \int_0^1 du \int_u^1 dv ue^v = \frac{1}{2} \int_0^1 ue^v \Big|_u^1 = \frac{1}{2} \int_0^1 du eu - ue^u = \\ &= \frac{1}{2} \left(\frac{e}{2} u^2 \Big|_0^1 - ue^u \Big|_0^1 + \int_0^1 e^u \right) = \frac{1}{2} \left(\frac{e}{2} - e + e - 1 \right) = \frac{e}{4} - \frac{1}{2} \end{aligned}$$

8. $D = \{(x, y, z) \in \mathbb{R}^3 : \max\{|x|, |y|, |z|\} \leq 1 \leq x^2 + y^2 + z^2\}$ $f(x, y) = x^2 y^2 z^2$



Notiamo che $D = D_1 \setminus D_2$ dove $D_1 = \{(x, y, z) \in \mathbb{R}^3 : \max\{|x|, |y|, |z|\} \leq 1\}$ e D_2 è la palla unitaria di \mathbb{R}^3 $D_2 = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 1\}$.

Per il teorema di Fubini abbiamo che

$$\int_{D_1} f(x, y, z) dx dy dz = \int_{-1}^1 dx \int_{-1}^1 dy \int_{-1}^1 dz x^2 y^2 z^2 = 8 \int_0^1 dx x^2 \int_0^1 dy y^2 \int_0^1 dz z^2 = \frac{8}{27}$$

Passando alle coordinate sferiche abbiamo invece che

$$\begin{aligned} \int_{D_2} f(x, y, z) dx dy dz &= \int_0^1 d\rho \int_0^{2\pi} d\theta \int_0^\pi d\varphi f(\rho \cos \theta \sin \varphi, \rho \sin \theta \sin \varphi, \rho \cos \varphi) \rho^2 \sin \varphi = \\ &= \int_0^1 d\rho \int_0^{2\pi} d\theta \int_0^\pi d\varphi \rho^8 \cos^2 \theta \sin^2 \theta \sin^5 \varphi \cos^2 \varphi = \int_0^\pi d\varphi \int_0^{2\pi} d\theta \int_0^1 d\rho \frac{1}{4} \rho^8 \sin^2(2\theta) \sin^5 \varphi \cos^2 \varphi = \\ &= \frac{1}{36} \int_0^\pi d\varphi \int_0^{2\pi} d\theta \sin^2(2\theta) \sin^5 \varphi \cos^2 \varphi = \frac{1}{72} \int_0^\pi d\varphi \int_0^{4\pi} dt \sin^2(t) \sin^5 \varphi \cos^2 \varphi = \\ &= \frac{\pi}{36} \int_0^\pi \sin^5 \varphi \cos^2 \varphi \stackrel{t=\cos \varphi}{=} \frac{\pi}{36} \int_{-1}^1 (1 - t^2)^2 t^2 = \frac{\pi}{18} \int_0^1 (t^2 - 2t^4 + t^6) dt = \\ &= \frac{\pi}{18} \left(\frac{1}{3} - \frac{2}{5} + \frac{1}{7} \right) = \frac{\pi}{18} \frac{8}{105} = \frac{4}{945} \pi \end{aligned}$$

Pertanto

$$\int_D f(x, y, z) dx dy dz = \int_{D_1} f(x, y, z) dx dy dz - \int_{D_2} f(x, y, z) dx dy dz = \frac{8}{27} - \frac{4}{945} \pi$$

9. $E = \{x \in \mathbb{R}^3 : \langle Mx, x \rangle \leq 1\}$

Siccome D è simmetrica e definita positiva allora per il teorema spettrale esiste una

matrice ortogonale Q tale che $Q^T M Q = D = \begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{pmatrix}$. Consideriamo allora

il cambio di variabile $x = \Phi(y) = Qy$. Si noti che $|\det J\Phi| = |\det Q| = 1$ perché Q è ortogonale.

Inoltre $\Phi^{-1}(E) = \{y \in \mathbb{R}^3 : \langle MQy, Qy \rangle \leq 1\}$ ma $\langle MQy, Qy \rangle = \langle Q^T M Q y, y \rangle = \langle D y, y \rangle = \lambda_1 y_1^2 + \lambda_2 y_2^2 + \lambda_3 y_3^2$ quindi $\Phi^{-1}(E) = \{y \in \mathbb{R}^3 : \lambda_1 y_1^2 + \lambda_2 y_2^2 + \lambda_3 y_3^2 \leq 1\}$ è l'ellissoide in \mathbb{R}^3 centrato nell'origine avente semiassi di lunghezze $\frac{1}{\sqrt{\lambda_1}}, \frac{1}{\sqrt{\lambda_2}}, \frac{1}{\sqrt{\lambda_3}}$. Per la formula del cambiamento di variabile abbiamo quindi che

$Vol(E) = \int_E 1 dx_1 dx_2 dx_3 = \int_{\Phi^{-1}(E)} 1 dy_1 dy_2 dy_3$. Consideriamo ora il cambio di vari-

abile $(z_1, z_2, z_3) = \Psi(y_1, y_2, y_3) = (\sqrt{\lambda_1} y_1, \sqrt{\lambda_2} y_2, \sqrt{\lambda_3} y_3)$. Dato che $\Psi^{-1}(\Phi^{-1}(E)) = \{(z_1, z_2, z_3) : z_1^2 + z_2^2 + z_3^2 \leq 1\} = B_1(0)$ è la palla unitaria di \mathbb{R}^3 e $\det J\Psi = \sqrt{\lambda_1} \sqrt{\lambda_2} \sqrt{\lambda_3}$ abbiamo

$$Vol(E) = \int_{\Phi^{-1}(E)} 1 dy_1 dy_2 dy_3 = \int_{B_1(0)} \sqrt{\lambda_1} \sqrt{\lambda_2} \sqrt{\lambda_3} dz_1 dz_2 dz_3 = \sqrt{\lambda_1} \sqrt{\lambda_2} \sqrt{\lambda_3} Vol(B_1(0)) =$$

$$= \frac{4}{3} \pi \sqrt{\lambda_1} \sqrt{\lambda_2} \sqrt{\lambda_3} = \frac{4}{3} \pi \sqrt{\det M}$$