# Spectral theory for linearized $p$-Laplace equations 

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#### Abstract

We continue and completely set up the spectral theory initiated in Castorina et al. (2009) [5] for the linearized operator arising from $\Delta_{p} u+f(u)=0$. We establish existence and variational characterization of all the eigenvalues, and by a weak Harnack inequality we deduce Hölder continuity for the corresponding eigenfunctions, this regularity being sharp. The Morse index of a positive solution can be now defined in the classical way, and we will illustrate some qualitative consequences one should expect to deduce from such information. In particular, we show that zero Morse index (or more generally, nondegenerate) solutions on the annulus are radial.


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## 1. Introduction

Let $u \in C^{1, \alpha}(\Omega)$ be a weak solution of the problem

$$
\begin{cases}-\Delta_{p} u=f(u) & \text { in } \Omega  \tag{1.1}\\ u>0 & \text { in } \Omega \\ u=0 & \text { on } \partial \Omega,\end{cases}
$$

where $\Omega$ is a bounded smooth domain in $\mathbb{R}^{N}, N \geqslant 2, \Delta_{p} u=\operatorname{div}\left(|D u|^{p-2} D u\right)$ is the $p$-Laplace operator, and $f$ is a positive $(f(s)>0$ for $s>0)$ locally Lipschitz continuous nonlinearity. The Hölder continuity of $\nabla u$ is in general optimal [1-3] and Eq. (1.1) is always meant in a weak sense.
The linearized operator $L_{u}$ associated to (1.1) at a given solution $u$ is defined by duality as $L_{u}: v \in H_{0} \rightarrow L_{u}(v) \in H_{0}^{\prime}$, where $L_{u}(v): \varphi \in H_{0} \rightarrow L_{u}(v, \varphi)$ and

$$
\begin{equation*}
L_{u}(v, \varphi):=\int_{\Omega}|\nabla u|^{p-2}(\nabla v, \nabla \varphi)+(p-2) \int_{\Omega}|\nabla u|^{p-4}(\nabla u, \nabla v)(\nabla u, \nabla \varphi)-\int_{\Omega} f^{\prime}(u) v \varphi \tag{1.2}
\end{equation*}
$$

The Hilbert space $H_{0}$ will be rigorously introduced in Section 2 according to [4] and is roughly composed by functions $v$ vanishing on the boundary so that $\int_{\Omega}|\nabla u|^{p-2}|\nabla v|^{2}<\infty$. In this way, the operator $L_{u}$ is well defined, and in [5] it is shown that the first eigenvalue of $L_{u}$

$$
\mu_{1}=\inf _{v \in H_{0}, v \neq 0} \frac{L_{u}(v, v)}{\int_{\Omega} v^{2}}
$$

is simple and attained at a nonnegative first eigenfunction $v_{1}$. The study in [5] can be pushed further to set up a complete spectral theory for $L_{u}$ as summarized in the following.

[^0]Theorem 1.1. The eigenvalues of $L_{u}$ have finite multiplicity and form a sequence

$$
\mu_{1}<\mu_{2} \leq \mu_{3} \leq \cdots
$$

(with repetitions according to the multiplicity) so that $\mu_{j} \rightarrow+\infty$ as $\rightarrow \infty$. Moreover, the $\mu_{j}$ 's can be characterized variationally as

$$
\begin{equation*}
\mu_{j}=\min _{\substack{V \subset H_{0} \\ \operatorname{dim} V=j}} \max _{v \in V, v \neq 0} \frac{L_{u}(v, v)}{\int_{\Omega} v^{2}}=\min _{\substack{V \subset H_{0} \\ \operatorname{dim} V=j-1}} \min _{v \in V^{\perp}, v \neq 0} \frac{L_{u}(v, v)}{\int_{\Omega} v^{2}} \tag{1.3}
\end{equation*}
$$

where the orthogonal space $V^{\perp}$ is meant in the $L^{2}(\Omega)$-sense. The corresponding eigenfunctions $v_{j} \in H_{0}$ solve the equation

$$
L_{u}\left(v_{j}, \varphi\right)=\mu_{j} \int_{\Omega} v_{j} \varphi \quad \forall \varphi \in H_{0}
$$

and form an orthonormal basis in $L^{2}(\Omega)$. Moreover, $v_{j}$ belongs to $C^{0, \alpha}(\Omega)$ for some $\alpha \in(0,1)$ provided $p>\frac{2 N+2}{N+2}$.
The existence of $\mu_{j}$ 's is based on the Fredholm alternative and makes a crucial use of the compact embedding $H_{0} \hookrightarrow L^{2}(\Omega)$ as established in [5]. The Hölder regularity of $v_{j}$ follows by a weak Harnack inequality and is essentially optimal. Indeed, the derivatives of $u$ are in the kernel of the linearized operator (but they do not fulfill the zero boundary condition) and are in general just Hölder continuous.
Once the spectral theory for $L_{u}$ is available, one can classically define the notion of Morse index $m(u)$ and non-degeneracy for a solution $u$ of (1.1). We believe that an information on $m(u)$ should carry relevant properties on $u$. From a qualitative viewpoint, this is well explained by the following.

Theorem 1.2. Let $\Omega$ be a bounded radially symmetric domain and $u$ be a solution of (1.1). Assume that either $m(u)=0$ or $u$ is a non-degenerate solution. Then, $u$ is radially symmetric.
The assumption $m(u)=0$ is simply equivalent to the semi-stability of $u$ : $L_{u}(v, v) \geqslant 0$ for all $v \in H_{0}$. The latter condition has been used (for $v$ in a suitable space of test functions) as a definition of semi-stability in cases where a spectral theory was not available or not attainable (see [6,7] and references therein). When $\Omega$ is a ball, the radial symmetry of $u$ follows by the moving plane method in [4] and the difficult case concerns the annulus.

Notice that any local minimum point $u$ of the corresponding energy functional actually satisfies $m(u)=0$, since the bilinear form $L_{u}$ represents the second derivative of the energy functional. Noticing that in general $H_{0} \neq W_{0}^{1, p}(\Omega)$ and that the energy functional is not $C^{2}$ even in $W_{0}^{1, p}(\Omega)$ when $p<2$, the computation of such a second derivative is a very delicate issue which has been established to hold exactly in $H_{0}$ (see [5]).

When $f(u)$ is replaced by $\lambda f(u)$, the corresponding nonlinear eigenvalue problem admits, in several situations, a branch $u_{\lambda}$ of minimal solutions - for $\lambda$ in a natural range - with $m\left(u_{\lambda}\right)=0$ (see $[6,5]$ and references therein). For $p=2$ and nondecreasing convex nonlinearities $f(u)$, it is well known that $u_{\lambda}$ is the unique zero Morse index solution, which is also radial when $\Omega$ is an annulus. In this respect, Theorem 1.2 is still already known on the annulus when $p=2$. However, for $p \neq 2$ it is not known that zero Morse index solutions need to be unique and Theorem 1.2 is no longer obvious. Such an uniqueness has been shown [8] to hold for radial solutions on the ball and $1<p \leq 2$.

Let us provide a last example. For a subcritical exponent $q\left(p-1<q<\frac{N(p-1)+p}{N-p}\right.$ when $p<N$ and $p-1<q<\infty$ when $p \geq N)$, the compact embedding $W_{0}^{1, p}(\Omega) \hookrightarrow L^{q+1}(\Omega)$ yields to a minimizer $u>0$ of

$$
m_{q}=\inf _{u \in W_{0}^{1, p}(\Omega), u \neq 0} \frac{\int_{\Omega}|\nabla u|^{p}}{\left(\int_{\Omega}|u|^{q+1}\right)^{\frac{p}{q+1}}}
$$

The function $u$ can be normalized to give a solution of (1.1) with $f(u)=m_{q} u^{q}$ corresponding to a Mountain Pass solution and $m(u)=1$. Indeed, since $u \in H_{0}$ and $\int_{\Omega}|u|^{q+1}=1$ we can easily compute $L_{u}(u, u)=m_{q}(p-1-q)<0$ so as to have $\mu_{1}<0$. On the other hand, we can fix $v \in H_{0}$ and compute

$$
\frac{\mathrm{d}^{2}}{\mathrm{~d} t^{2}} \frac{\int_{\Omega}|\nabla(u+t v)|^{p}}{\left(\int_{\Omega}|u+t v|^{q+1}\right)^{\frac{p}{q+1}}}=p L_{u}(v, v)+p m_{q}(q-p+1)\left(\int_{\Omega} u^{q} v\right)^{2}
$$

Since $u$ is a minimizer, we get that $L_{u}(v, v) \geq 0$ for every $v \in V=\left\{v \in H_{0}: \int_{\Omega} u^{q} v=0\right\}$ and by Theorem 1.1 we deduce $\mu_{2} \geq 0$ so as to establish $m(u)=1$.
Starting from [9-11], there has been an intensive study of the nonlinear eigenvalues $\lambda_{j}$ 's of $-\Delta_{p}$ but still very little is known. They have been used to obtain, by non-standard variational methods, solutions of $-\Delta_{p} u-\lambda|u|^{p-2} u=f(u)$. There is a large literature on this topic. We refer the reader in particular to [12] and to [13,14](see also the references therein).

The linear eigenvalues $\mu_{j}$ 's play the same role here as the eigenvalues of $-\Delta-f^{\prime}(u)$ but the picture is more complicate due to the degenerate and nonlinear nature of $-\Delta_{p}$. First, one might wonder if the non-degeneracy of a solution $u$ allows for
a local analysis in the spirit of the Implicit Function Theorem. Recall that here the energy functional is not $C^{2}$ and the space $H_{0}$ depends on the solution itself. Secondly, regularity and compactness results for finite Morse index solutions should be in order in low dimensions (depending on the nonlinearity), as it has been already established for $p=2$ [15-18]. Finally, it would be really of interest, the study of symmetry properties for finite Morse index solutions as in the case $p=2$ [19], a flavor of it having been given in Theorem 1.2.

## 2. Spectral theory for $\boldsymbol{L}_{u}$

Given a solution $u$ of (1.1), for $p \geq 2$ we define the Hilbert space $H=H_{\rho}^{1,2}(\Omega), \rho=|\nabla u|^{p-2}$, where (as in [4]) $H_{\rho}^{1,2}(\Omega)$ is the completion of $C^{\infty}(\Omega)$ w.r.t. the norm

$$
\begin{equation*}
\|v\|_{H}^{2}=\int_{\Omega} v^{2}+\int_{\Omega}|\nabla u|^{p-2}|\nabla v|^{2} . \tag{2.4}
\end{equation*}
$$

Since $\Omega$ is smooth, $H$ is equivalently composed by the functions $v$ which have distributional derivative and satisfy $\|v\|_{H}<$ $\infty$. The space $H_{0}$ is defined as the completion of $C_{0}^{\infty}(\Omega)$ w.r.t. the norm $\|\cdot\|_{H}$. Letting $\|v\|_{H_{0}}^{2}=\int_{\Omega}|\nabla u|^{p-2}|\nabla v|^{2}$ for every $v \in H_{0}$, the following Sobolev inequality does hold [4]:

$$
\begin{equation*}
\|v\|_{L^{q}(\Omega)} \leq S_{q}\|v\|_{H_{0}} \quad \forall v \in H_{0} \tag{2.5}
\end{equation*}
$$

where $1 \leqslant q<\frac{2 N(p-1)}{N(p-1)-2}$ and $S_{q}>0$ is a positive constant. In particular, for $q=2(2.5)$ provides a Poincaré inequality which implies the equivalence in $H_{0}$ of the two norms $\|\cdot\|_{H}$ and $\|\cdot\|_{H_{0}}$. Moreover, the embedding $H_{0} \hookrightarrow L^{q}(\Omega)$ is compact for any $1 \leq q<\frac{2 N(p-1)}{N(p-1)-2}$, (see [5]). Since $C_{0}^{\infty}(\Omega) \subset H_{0}$, we also have that $H_{0}$ is dense in $L^{2}(\Omega)$.

For $1<p<2$, we define $H_{0}$ simply as

$$
H_{0}=\left\{v \in H_{0}^{1}(\Omega):\|v\|_{H_{0}}<\infty\right\}
$$

Since $\|v\|_{H_{0}^{1}} \leqslant\|\nabla u\|_{\infty}^{\frac{2-p}{2}}\|v\|_{H_{0}}$, it follows that $H_{0}$ is compactly embedded in $L^{q}(\Omega)$, for any $1 \leq q<\frac{2 N}{N-2}$. Since $Z_{u}=$ $\{x \in \bar{\Omega}: \nabla u(x)=0\} \subset \Omega$ has zero Lebesgue measure [4], we can always approximate a function $v \in L^{2}(\Omega)$ by a sequence $v_{n} \in C_{0}\left(\Omega \backslash Z_{u}\right) \cap H^{1}(\Omega) \subset H_{0}$ so as to provide the density of $H_{0}$ in $L^{2}(\Omega)$. In conclusion, $H_{0}$ is dense and embeds compactly in $L^{2}(\Omega)$ for every $p>1$.
To develop the linear theory for $L_{u}$ as contained in Theorem 1.1, we exploit a standard procedure which may be found for example in [20].

First, for $\Lambda \in \mathbb{R}$ we let

$$
a_{\Lambda}(v, w):=L_{u}(v, w)+\Lambda \int_{\Omega} v w \quad \forall v, w \in H_{0}
$$

Through the Hölder and the (weighted) Poincaré inequalities, it is easy to see that $a_{\Lambda}$ is continuous: $\left|a_{\Lambda}(v, w)\right| \leq$ $C\|v\|_{H_{0}}\|w\|_{H_{0}}$. Furthermore, if we set $C_{1}=\min \{p-1,1\}$ and $C_{2}=\max \{p-1,1\}$, since

$$
C_{1}|\nabla u|^{p-2}|\nabla v|^{2} \leq|\nabla u|^{p-2}|\nabla v|^{2}+(p-2)|\nabla u|^{p-4}(\nabla u, \nabla v)^{2} \leq C_{2}|\nabla u|^{p-2}|\nabla v|^{2},
$$

we can achieve the coercivity of $a_{\Lambda}: a_{\Lambda}(v, v) \geq C_{0}\|v\|_{H_{0}}^{2}$ for $C_{0}>0$, whenever $\Lambda \geq\left\|f^{\prime}(u)\right\|_{\infty}$. By the Lax-Milgram theorem, we can then define the resolvent operator $G: f \in L^{2}(\Omega) \rightarrow G_{f} \in H_{0}$, where $G_{f}$ is the unique solution of

$$
a_{\Lambda}\left(G_{f}, w\right)=\int_{\Omega} f w \quad \forall w \in H_{0}
$$

Now $G: L^{2}(\Omega) \rightarrow L^{2}(\Omega)$ is clearly a self-adjoint operator by the symmetry of $a_{\Lambda}$, whereas its compactness follows by the estimate

$$
C_{0}\left\|G_{f}\right\|_{H_{0}}^{2} \leq a_{\Lambda}\left(G_{f}, G_{f}\right)=\int_{\Omega} f G_{f} \leq S_{2}\|f\|_{L^{2}}\left\|G_{f}\right\|_{H_{0}}
$$

and the compact embedding $H_{0} \hookrightarrow L^{2}(\Omega)$.
By the Riesz-Fredholm theory, the eigenvalues $\beta_{j}$ 's of $G$ have finite multiplicity and form a sequence of positive numbers which converges to zero. It is clear that $(\beta, v)$ is an eigenpair of $G$ if and only if $a_{\Lambda}(v, \varphi)=\beta^{-1} \int_{\Omega} v \varphi$ does hold for every $\varphi \in H_{0}$. Hence, the linearized operator $L_{u}$ has a sequence of eigenvalues $\mu_{j}=\beta_{j}^{-1}-\Lambda \rightarrow+\infty$ of finite multiplicity:

$$
\mu_{1}<\mu_{2} \leqslant \mu_{3} \leqslant \cdots
$$

(with repetitions according to the multiplicity). The corresponding eigenfunction $v_{j} \in H_{0}$ satisfies $L_{u}\left(v_{j}, \varphi\right)=\mu_{j} \int_{\Omega} v_{j} \varphi$ for all $\varphi \in H_{0}$. By the self-adjointness of $G$ the $v_{j}$ 's can be normalized so as to form an orthonormal basis in $L^{2}(\Omega)$. The operator $G$ can be also seen as acting from $H_{0}$ into itself, and is still a compact self-adjoint operator whenever $H_{0}$ is endowed with
the equivalent norm $|v|^{2}=a_{\Lambda}(v, v)$. Since $v_{j} \in H_{0}$, also in this case $G$ has the $\beta_{j}$ 's as eigenvalues and the renormalization $\tilde{v}_{j}=\beta_{j}^{\frac{1}{2}} v_{j}$ form an orthonormal basis in $H_{0}$ in view of

$$
a_{\Lambda}\left(\tilde{v}_{j}, \tilde{v}_{k}\right)=\beta_{k}^{\frac{1}{2}} \beta_{j}^{-\frac{1}{2}} \int_{\Omega} v_{j} v_{k}=\delta_{j k}
$$

Recall that $\mu_{1}$ is simple and satisfies (1.3) in view of

$$
\mu_{1}=\min _{v \in H_{0}, v \neq 0} \frac{L_{u}(v, v)}{\int_{\Omega} v^{2}}
$$

and the associated eigenspace is one-dimensional, generated by a first nonnegative eigenfunction $v_{1}$. Setting

$$
\mathcal{R}(v)=\frac{L_{u}(v, v)}{\int_{\Omega} v^{2}}
$$

we can compute

$$
\mathcal{R}(v)=\frac{\sum_{k=1}^{j} \alpha_{k}^{2} \mu_{k}}{\sum_{k=1}^{j} \alpha_{k}^{2}} \leq \mu_{j}
$$

for every $v=\sum_{k=1}^{j} \alpha_{k} v_{k} \in \operatorname{Span}\left\{v_{1}, \ldots, v_{j}\right\}, v \neq 0$. Since the equality holds when $\alpha_{1}=\cdots=\alpha_{j-1}=0$ and $\alpha_{j}=1$, we get that

$$
\begin{equation*}
\mu_{j}=\max _{v \in \operatorname{Span}\left\{v_{1}, \ldots, v_{j} \backslash \backslash\{0\}\right.} \mathcal{R}(v) \tag{2.6}
\end{equation*}
$$

Given $v \perp v_{1}, \ldots, v_{j-1}$ in $L^{2}(\Omega)$, we have that

$$
v=\sum_{k=j}^{\infty} \alpha_{k} v_{k}, \quad \alpha_{k}=\int_{\Omega} v v_{k}
$$

in $L^{2}(\Omega)$, so as to get

$$
\int_{\Omega} v^{2}=\sum_{k=j}^{\infty} \alpha_{k}^{2}
$$

Since

$$
a_{\Lambda}\left(\tilde{v}_{k}, v\right)=\beta_{k}^{-\frac{1}{2}} \int_{\Omega} v v_{k} \quad \forall k \in \mathbb{N}
$$

similarly we have that

$$
v=\sum_{k=j}^{\infty} \tilde{\alpha}_{k} \tilde{v}_{k}, \quad \tilde{\alpha}_{k}=\beta_{k}^{-\frac{1}{2}} \alpha_{k}
$$

in $\left(H_{0},|\cdot|\right)$, and then

$$
a_{\Lambda}(v, v)=\sum_{k=j} \beta_{k}^{-1} \alpha_{k}^{2}=\sum_{k=j}\left(\mu_{k}+\Lambda\right) \alpha_{k}^{2}
$$

Hence, we deduce that

$$
\mathcal{R}(v)=\frac{\sum_{k=j}^{\infty} \mu_{k} \alpha_{k}^{2}}{\sum_{k=j}^{\infty} \alpha_{k}^{2}} \geq \mu_{j}
$$

and in turn

$$
\begin{equation*}
\mu_{j}=\min _{v \perp v_{1}, \ldots, v_{j-1}} \mathcal{R}(v) \tag{2.7}
\end{equation*}
$$

Given $V$ with $\operatorname{dim} V=j$, we can always find $\bar{v} \in V, \bar{v} \neq 0$, such that $\bar{v} \perp v_{1} \ldots, v_{j-1}$, and by (2.7) we get that

$$
\max _{v \in V, v \neq 0} \mathcal{R}(v) \geqslant \mu_{j}
$$

and in turn

$$
\mu_{j}=\min _{\substack{V \subset H_{0} \\ \operatorname{dim} V=j}} \max _{v \in V, v \neq 0} \mathcal{R}(v)
$$

does hold since by (2.6) the minimum is achieved exactly at $V=\operatorname{Span}\left\{v_{1}, \ldots, v_{j}\right\}$. The first relation in (1.3) has been established. As far as the second one, similarly, we can deduce by (2.6) that

$$
\min _{v \in V^{\perp}, v \neq 0} \mathcal{R}(v) \leqslant \mu_{j}
$$

for every $V$ such that $\operatorname{dim} V=j-1$. Hence, there holds

$$
\mu_{j}=\max _{\substack{V \subset H_{0} \\ \operatorname{dim} V=j-1}} \min _{v \in V^{\perp}, v \neq 0} \mathcal{R}(v)
$$

since by (2.7) the maximum is achieved exactly at $V=\operatorname{Span}\left\{v_{1}, \ldots, v_{j-1}\right\}$. The first part of Theorem 1.1 has been completely established.

## 3. $C^{0, \alpha}$-regularity of the eigenfunctions

We prove here that any eigenfunction of the linearized operator $L_{u}$ is Hölder continuous. To this aim, we prove a Harnack inequality for an operator slightly more general than $L_{u}$, i.e.

$$
\begin{equation*}
\mathcal{L}(v, \varphi)=\int_{\Omega}|\nabla u|^{p-2}(\nabla v, \nabla \varphi)+(p-2) \int_{\Omega}|\nabla u|^{p-4}(\nabla u, \nabla v)(\nabla u, \nabla \varphi)-\int_{\Omega} c v \varphi-\int_{\Omega} g \varphi \tag{3.8}
\end{equation*}
$$

for $v, \varphi \in H_{0}$, where $c, g \in L^{\infty}(\Omega)$.
We can prove the following weak Harnack inequality for $\mathcal{L}$ :
Theorem 3.1. Let $v \in H \cap L^{\infty}(\Omega)$ be a nonnegative weak supersolution of (3.8). For $p>2$, consider $s$ so that $0<s<$ $\frac{N(p-1)}{(N-2)(p-1)+2(p-2)}$ and $x_{0} \in \Omega$ so that $B\left(x_{0}, 5 R\right) \subset \Omega$. Then we find a constant $C>0$ such that

$$
\begin{equation*}
R^{-\frac{n}{s}}\|v\|_{L^{s}\left(B\left(x_{0}, 2 R\right)\right)} \leq C\left(\inf _{B\left(x_{0}, R\right)} v+R^{p}\|g\|_{L^{\infty}}\right) \tag{3.9}
\end{equation*}
$$

If $\frac{2 N+2}{N+2}<p<2$ the same result holds for $0<s<\frac{2^{*}}{s^{\sharp}}$, with $\frac{2}{s^{\sharp}}=1-\frac{1}{s}$ and $s<\frac{p-1}{2-p}$.
Proof. The function $v$ solves $\mathcal{L}(v, \varphi) \geq 0$ for any $0 \leq \varphi \in H_{0}$. Remark that we may always assume $v \geq \tau>0$. Otherwise, we can consider $v+\tau$, replace $g$ by $g+\tau c$ and let $\tau \rightarrow 0$. Rescaling (3.8) with $y=\frac{x-x_{0}}{R}$ we get

$$
\begin{equation*}
\int_{\Omega^{\prime}}\left[\left|\nabla u^{\prime}\right|^{p-2}\left(\nabla v^{\prime}, \nabla \varphi\right)+(p-2)\left|\nabla u^{\prime}\right|^{p-4}\left(\nabla u^{\prime}, \nabla v^{\prime}\right)\left(\nabla u^{\prime}, \nabla \varphi\right)-\tilde{c} v^{\prime} \varphi-\tilde{g} \varphi\right] \geq 0 \tag{3.10}
\end{equation*}
$$

where $\Omega^{\prime}=\frac{\Omega-x_{0}}{R}, w^{\prime}(y)=w\left(x_{0}+R y\right)$ for every function $w$ in $\Omega, \tilde{c}=R^{p} c^{\prime}$ and $\tilde{g}=R^{p} g^{\prime}$. Inequality (3.10) does hold for every $\phi \in H_{0}^{\prime}$, where $H_{0}^{\prime}$ is defined as $H_{0}$ with $\Omega, u$ replaced by $\Omega^{\prime}, u^{\prime}$. Consider the function $\tilde{v}$ defined by $\tilde{v}=v^{\prime}+\|\tilde{g}\|_{\infty}$. Taking into account (3.10) it follows that $\tilde{v}$ fulfills

$$
\begin{equation*}
\int_{\Omega^{\prime}}\left[\left|\nabla u^{\prime}\right|^{p-2}(\nabla \tilde{v}, \nabla \varphi)+(p-2)\left|\nabla u^{\prime}\right|^{p-4}\left(\nabla u^{\prime}, \nabla \tilde{v}\right)\left(\nabla u^{\prime}, \nabla \varphi\right)-\bar{c} \tilde{v} \varphi\right] \geq 0 \tag{3.11}
\end{equation*}
$$

for all $\varphi \in H_{0}^{\prime}$, with $\bar{c}=\left(\tilde{c} v^{\prime}+\tilde{g}\right) \tilde{v}^{-1}$. Since the zero order coefficient is bounded:

$$
|\bar{c}(y)| \leq\left|\frac{\tilde{c}(y) v^{\prime}(y)}{v^{\prime}(y)+\|\tilde{g}\|_{\infty}}\right|+\left|\frac{\tilde{g}}{v^{\prime}(y)+\|\tilde{g}\|_{\infty}}\right| \leq\|\tilde{c}\|_{\infty}+1<\infty
$$

we can develop an iterative Moser-type scheme [21] to prove a weak Harnack inequality for $\tilde{v}$. For all the details of the proof, we refer the readers to the Appendix of [22], where the iterative Moser-type technique was developed in a similar setting in the spirit of [23]. Here we only start the procedure taking care of the fact that the operator we are considering is more general than the one in [22].

We define

$$
\phi \equiv \eta^{2} \tilde{v}^{\beta}, \quad \beta<0
$$

with $0 \leq \eta \in C_{0}^{1}(B(0,5))$. Since $\nabla \phi=2 \eta \tilde{v}^{\beta} \nabla \eta+\beta \eta^{2} \tilde{v}^{\beta-1} \nabla \tilde{v}$, we have that $\phi \in H_{0}^{\prime}$ and then can be used as a test function in (3.11) so as to get

$$
\begin{aligned}
& \int_{\Omega^{\prime}}\left[\beta \rho^{\prime}|\nabla \tilde{v}|^{2} \eta^{2} \tilde{v}^{\beta-1}+\beta(p-2)\left|\nabla u^{\prime}\right|^{p-4}\left(\nabla u^{\prime}, \nabla \tilde{v}\right)^{2} \eta^{2} \tilde{v}^{\beta-1}\right] \\
& \quad+\int_{\Omega^{\prime}}\left[2 \eta \tilde{v}^{\beta} \rho^{\prime}(\nabla \tilde{v}, \nabla \eta)+2 \eta(p-2) \tilde{v}^{\beta}\left|\nabla u^{\prime}\right|^{p-4}\left(\nabla u^{\prime}, \nabla \eta\right)\left(\nabla u^{\prime}, \nabla \tilde{v}\right)\right] \\
& \geqslant \int_{\Omega^{\prime}} \bar{c} \eta^{2} \tilde{v}^{\beta+1}
\end{aligned}
$$

where $\rho^{\prime}=\left|\nabla u^{\prime}\right|^{p-2}$. Note that the weight that appears in $[4]$ is $\rho=|\nabla u|^{p-2}$, and the properties of this weight are crucial. Our rescaled weight has the same summability properties and everything works.

Since $\beta<0$, for $p>2$ the term $\beta(p-2)\left|\nabla u^{\prime}\right|^{p-4}\left(\nabla u^{\prime}, \nabla \tilde{v}\right)^{2} \eta^{2} \tilde{v}^{\beta-1}$ is negative and we have

$$
\beta \rho^{\prime}|\nabla \tilde{v}|^{2} \eta^{2} \tilde{v}^{\beta-1}+\beta(p-2)\left|\nabla u^{\prime}\right|^{p-4}\left(\nabla u^{\prime}, \nabla \tilde{v}\right)^{2} \eta^{2} \tilde{v}^{\beta-1} \leq \beta \rho^{\prime}|\nabla \tilde{v}|^{2} \eta^{2} \tilde{v}^{\beta-1}
$$

For $1<p<2$ we can use the fact that $\beta(p-2)>0$ to show

$$
\beta \rho^{\prime}|\nabla \tilde{v}|^{2} \eta^{2} \tilde{v}^{\beta-1}+\beta(p-2)\left|\nabla u^{\prime}\right|^{p-4}\left(\nabla u^{\prime}, \nabla \tilde{v}\right)^{2} \eta^{2} \tilde{v}^{\beta-1} \leq(p-1) \beta \rho^{\prime}|\nabla \tilde{v}|^{2} \eta^{2} \tilde{v}^{\beta-1}
$$

In conclusion, for every $p>1$ we get that

$$
\min \{1, p-1\}|\beta| \int_{\Omega^{\prime}} \rho^{\prime}|\nabla \tilde{v}|^{2} \eta^{2} \tilde{v}^{\beta-1} \leqslant 2(p-1) \int_{\Omega^{\prime}} \rho^{\prime} \eta \tilde{v}^{\beta}|\nabla \tilde{v}||\nabla \eta|+\int_{\Omega^{\prime}}|\bar{c}| \eta^{2} \tilde{v}^{\beta+1}
$$

By the Young's inequality $2(p-1) a b \leqslant \min \{1, p-1\}|\beta| a^{2} \backslash 2+2(p-1)^{2} b^{2} \backslash|\beta| \min \{1, p-1\}$ we obtain

$$
\min \{1, p-1\} \frac{|\beta|}{2} \int_{\Omega^{\prime}} \rho^{\prime}|\nabla \tilde{v}|^{2} \eta^{2} \tilde{v}^{\beta-1} \leqslant \frac{C_{2}}{|\beta|} \int_{\Omega^{\prime}} \rho^{\prime} \tilde{v}^{\beta+1}|\nabla \eta|^{2}+\int_{\Omega^{\prime}}|\bar{c}| \eta^{2} \tilde{v}^{\beta+1}
$$

and by $\|\bar{c}\|_{\infty}<\infty$

$$
\begin{equation*}
\int_{\Omega^{\prime}} \rho^{\prime}|\nabla \tilde{v}|^{2} \eta^{2} \tilde{v}^{\beta-1} \leqslant \frac{C}{|\beta|}\left(1+\frac{1}{|\beta|}\right) \int_{\Omega^{\prime}} \tilde{v}^{\beta+1}\left[\eta^{2}+\rho^{\prime}|\nabla \eta|^{2}\right] . \tag{3.12}
\end{equation*}
$$

Let us now define

$$
w \equiv \begin{cases}\tilde{v}^{\frac{\beta+1}{2}} & \text { if } \beta \neq-1 \\ \log (\tilde{v}) & \text { if } \beta=-1\end{cases}
$$

and set $r \equiv \beta+1$. With these definitions we can write (3.12) as follows

$$
\int_{\Omega^{\prime}} \rho^{\prime} \eta^{2}|\nabla w|^{2} \leqslant\left\{\begin{array}{l}
C\left(1+\frac{1}{|\beta|}\right)^{2} \int_{\Omega^{\prime}} w^{2}\left[\eta^{2}+\rho^{\prime}|\nabla \eta|^{2}\right] \quad \beta \neq-1  \tag{3.13}\\
C_{0} \int_{\Omega^{\prime}}\left[\eta^{2}+\rho^{\prime}|\nabla \eta|^{2}\right] \quad \beta=-1
\end{array}\right.
$$

We have now that (3.13) is exactly (A.9) in [22]. We can therefore use the proof in [22] (from (A.9) to the end of the proof of Theorem 3.1) and get that there exists $C>0$ such that

$$
\|\tilde{v}\|_{L^{s}(B(0,2))} \leq C_{B(0,1)} \inf \tilde{v}
$$

Finally, scaling back to the coordinates $x=x_{0}+R y$ and recalling that $\tilde{v}=v^{\prime}+\|\tilde{g}\|_{\infty}=v^{\prime}+R^{p}\|g\|_{\infty}$ we get exactly Eq. (3.9).

Theorem 3.2. Let $u$ be a solution of (1.1) and $v_{i} \in H_{0}$ be any eigenfunction of the linearized operator $L_{u}$. Assume that $\frac{2 N+2}{N+2}<p<\infty$. There exists $\alpha \in(0,1)$ such that $v_{i} \in C_{\text {loc }}^{0, \alpha}(\Omega)$.
Proof. The eigenfunction $v=v_{i}$ solves

$$
\int_{\Omega}\left[|\nabla u|^{p-2}\left(\nabla v_{i}, \nabla \varphi\right)+(p-2)|\nabla u|^{p-4}\left(\nabla u, \nabla v_{i}\right)(\nabla u, \nabla \varphi)-\left(f^{\prime}(u)+\mu_{i}\right) v_{i} \varphi\right]=0
$$

for all $\varphi \in H_{0}$. Define $M_{k} \equiv \sup _{B\left(x_{0}, k R\right)} v$ and $m_{k} \equiv \inf _{B\left(x_{0}, k R\right)} v$. Considering the functions $M_{4}-v$ and $v-m_{4}$, we see that they are nonnegative supersolutions of (3.8) with $c(x)=-f^{\prime}(u)-\mu_{i}\left(\operatorname{resp} . c(x)=f^{\prime}(u)+\mu_{i}\right)$ and $g(x)=M_{4}\left(f^{\prime}(u)+\mu_{i}\right)$
(resp. $g(x)=m_{4}\left(f^{\prime}(u)+\mu_{i}\right)$ ), which are both bounded. Hence by Theorem 3.1 they satisfy (3.9) for any $0<s<\chi$, with $\chi>1$. Now, applying Eq. (3.9) with $s=1$ and adding up we can estimate

$$
\begin{aligned}
M_{4}-m_{4} & =c_{n} R^{-n} \int_{B\left(x_{0}, 2 R\right)}\left(M_{4}-v\right)+\left(v-m_{4}\right) \mathrm{d} x \\
& \leq C\left\{\left[\left(M_{4}-M_{1}\right)+\left(m_{1}-m_{4}\right)\right]+\left(M_{4}+m_{4}\right)\left(\left\|f^{\prime}(u)\right\|_{\infty}+\left|\mu_{i}\right|\right) R^{p}\right\} .
\end{aligned}
$$

Thus, if we set $\omega(k R)=M_{k}-m_{k}$ and $k(R)=2 M_{4}\left(\left\|f^{\prime}(u)\right\|_{\infty}+\left|\mu_{i}\right|\right) R^{p}$, we finally get the existence of $\gamma>0$ such that

$$
\begin{equation*}
\omega(R) \leq \gamma \omega(4 R)+k(R) . \tag{3.14}
\end{equation*}
$$

Since $k(R)$ is non-decreasing for any $R>0$, by (3.14) we can apply Lemma 8.23 page 201 of [24] to obtain that there exists $\alpha \in(0,1)$ such that

$$
\omega(R) \leq C R^{\alpha}
$$

This yields to the desired Hölder regularity and concludes the proof.

## 4. An application

We are now in position to follow the literature for the non-degenerate case and give the following
Definition 4.1. Let $u$ be any solution of (1.1). We define the Morse index $m(u)$ of $u$ as the number of negative eigenvalues of $L_{u}$ in $H_{0}$, i.e. $m(u)=j$ iff $\mu_{j}\left(L_{u}\right)<0$ and $\mu_{j+1}\left(L_{u}\right) \geq 0$. We say that $u$ is non-degenerate if 0 is not an eigenvalue of $L_{u}$, i.e. $\mu_{j}\left(L_{u}\right) \neq 0$ for any $j$.

According to Theorem 1.1 the Morse index $m(u)$ of $u$ defined as above is exactly the maximal dimension of a subspace of $H_{0}$ where $L_{u}$ is defined to be negative, the latter being a definition also used in a setting where a complete spectral theory is not available (see for example [18]).

We can then prove the following
Proposition 4.2. Let $u$ be a solution of (1.1) and $\Omega \subset \mathbb{R}^{N}$ be an annulus, $N \geq 2$. Assume that either $m(u)=0$ or $u$ is nondegenerate. Then, $u$ is radially symmetric.

Proof. For simplicity, let us start considering the case $N=2$. Taking into account the radial symmetry of $\Omega$, it is convenient to write $u=u(r, \theta)$ in polar coordinates, where $r=|x|$ and $\theta$ is the angular variable. Notice that, if $u$ is not radial, $u_{\theta}$ necessarily changes sign in $\Omega$. An explicit computation shows that there exists $C=C(\Omega, N)>0$ such that

$$
\begin{equation*}
\int_{\Omega}|\nabla u|^{p-2}\left|\nabla u_{\theta}\right|^{2} \leq C \int_{\Omega}|\nabla u|^{p-2}\left|D^{2} u\right|^{2} \tag{4.15}
\end{equation*}
$$

where $u_{\theta}$ is considered as a function of the variables $\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}$. By [4] we know that $u_{x_{i}} \in H$ for any $i=1, \ldots, N$, so as to provide the finiteness of the quantities in (4.15). Moreover, by the boundary conditions we see that $u_{\theta}=0$ on $\partial \Omega$.

This means that $u_{\theta} \in H_{0}$, so that we can plug it into the linearized equation (1.2). Moreover, integrating by parts in polar coordinates as in [4] (see Lemma 2.1), we have that

$$
\begin{equation*}
L_{u}\left(u_{\theta}, \varphi\right)=0 \quad \forall \varphi \in H_{0} \tag{4.16}
\end{equation*}
$$

That is, $u_{\theta}$ is an eigenfunction of the linearized operator with eigenvalue 0 . In this way, either $u_{\theta}=0$ in $\Omega$ or $u_{\theta}$ is the first eigenfunction of $L_{u}$ and has constant sign in $\Omega$. This necessarily implies that $u$ is radially symmetric.

For $N>2$, we can still write the solution $u=u(r, \theta)$ in polar coordinates, where $r=|x|$ and $\theta=\left(\theta_{1}, \ldots, \theta_{n-1}\right)$ are the $n-1$ angular variables. Notice that, also in this case, if $u$ is not radial, then $u_{\theta_{i}} \neq 0$ and $u_{\theta_{i}}$ changes sign, for some $i \in\{1, \ldots, n-1\}$. We can repeat the argument above for $u_{\theta_{i}}$ so as to show that necessarily $u$ is radial. This concludes the proof.

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