

Modeling of dislocations: from discrete models to the line-tension limit

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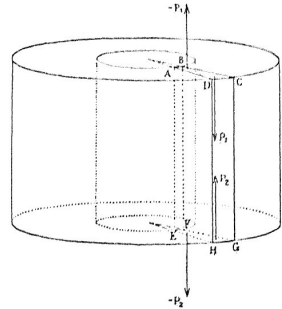
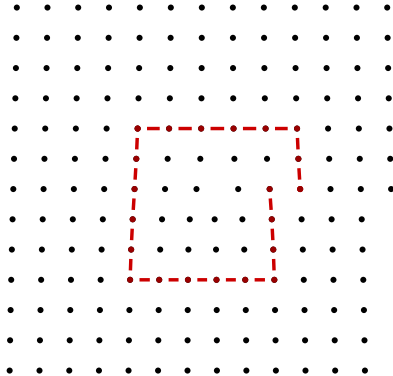


Based on joint work with Pilar Ariza (Sevilla), Adriana Garroni (Roma),
Stefan Müller (Bonn), Michael Ortiz (Bonn/Caltech)

Roma, 07.02.2023

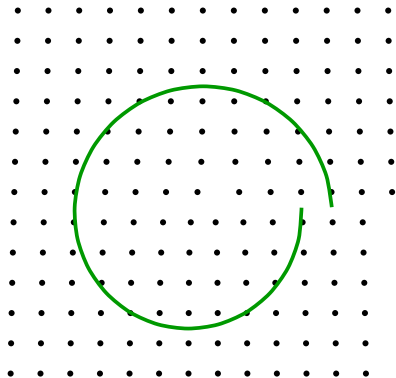


Dislocations in crystals



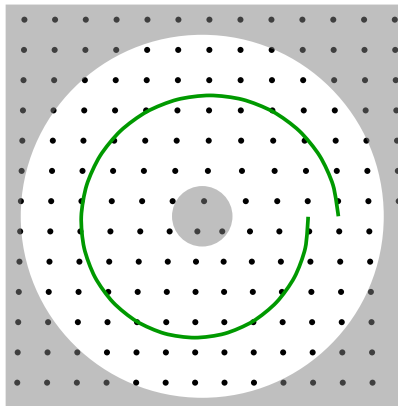
Vito Volterra, 1907

Dislocations in crystals



$$\int_{\partial B_r} |\beta| d\mathcal{H}^1 \geq \left| \int_{\partial B_r} \beta \cdot t d\mathcal{H}^1 \right| = |b|, \quad \int_{\partial B_r} |\beta|^2 d\mathcal{H}^1 \geq \frac{|b|^2}{2\pi r}$$

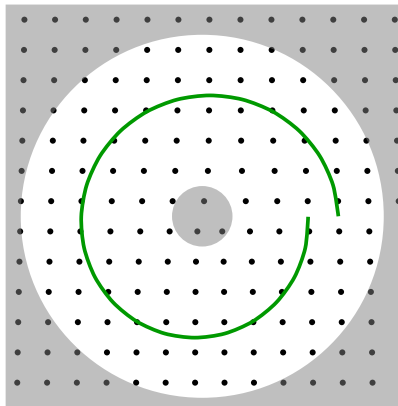
1. Dislocations in crystals



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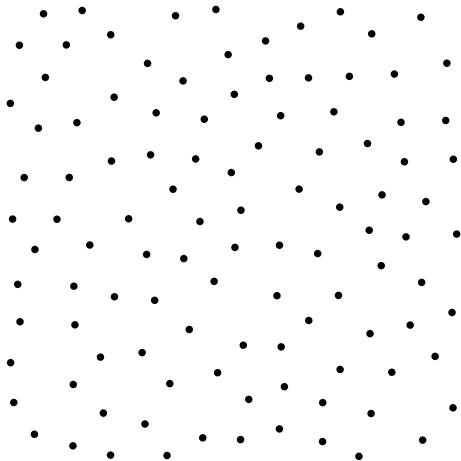
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1. Dislocations in crystals

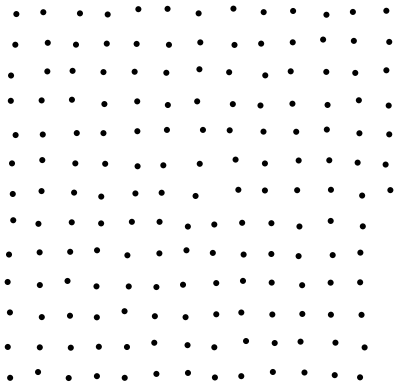


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$$\frac{1}{c} \int_{B_R \setminus B_\epsilon} |\beta + \beta^T|^2 \geq \int_{B_R \setminus B_\epsilon} |\beta|^2 \geq \frac{|b|^2}{2\pi} \ln \frac{R}{\epsilon}$$

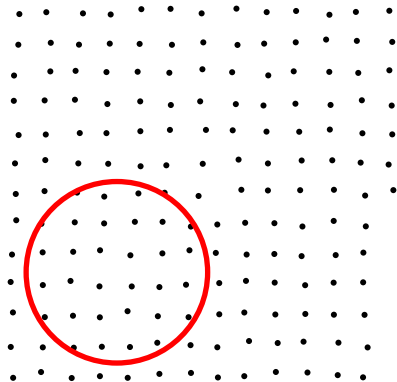


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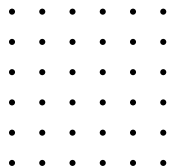
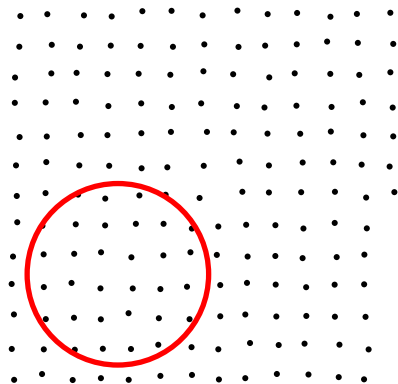


$$\sum_{i \neq j} V(|x_i - x_j|)?$$

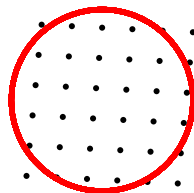
1.



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$$\mathbb{Z}^2 \mapsto F\mathbb{Z}^2 + a$$



$$P \subset \mathbb{R}^3$$

$$x \in \mathbb{R}^3, r > 0$$

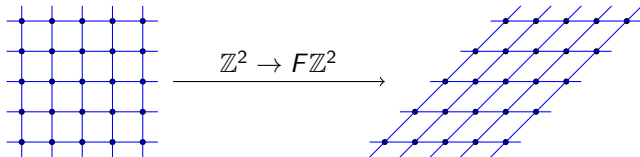
$$\min_{a \in \mathbb{R}^3, F \in \mathbb{R}^{3 \times 3}} D(P \cap B_r(x), (F\mathbb{Z}^3 + a) \cap B_r(x))$$

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$$F\mathbb{Z}^3 + a = G\mathbb{Z}^3 + b \text{ iff } G^{-1}F \in GL(3, \mathbb{Z}), G^{-1}(b - a) \in \mathbb{Z}^3$$



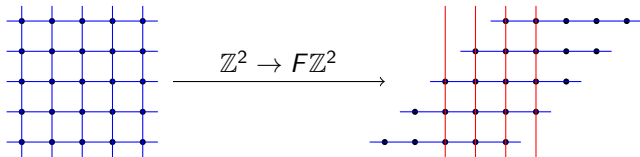
$$F = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \in GL(2, \mathbb{Z})$$

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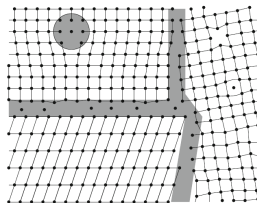
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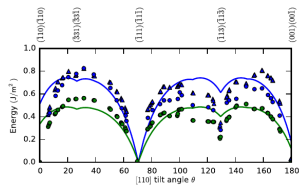
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Models for D ?

– Luckhaus-Mugnai 2010

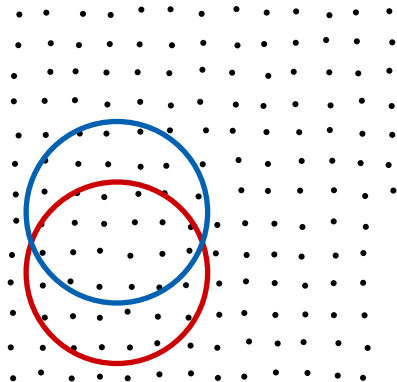


– Runnels-Beyerlein-SC-Ortiz 2016

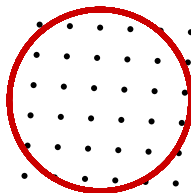
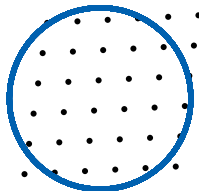


Grain boundary energy, Cu and Au (fcc)

–



$$\mathbb{Z}^2 \mapsto F\mathbb{Z}^2 + a$$



$$\mathbb{Z}^2 \mapsto G\mathbb{Z}^2 + a'$$

“Lemma”. Choose “minimal” F . If $D \ll 1$ in ω , then $\operatorname{curl} F = 0$ in ω

Elasticity: $F = \nabla u$, $E[u] = \int W(\nabla u) dx$

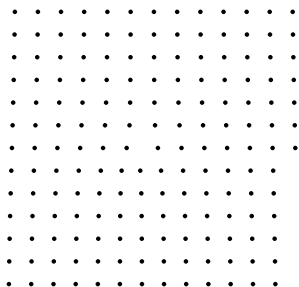
$(W(QFR) = W(F), Q \in SO(3), R \in GL(3, \mathbb{Z}))$

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Dislocation: $\omega = B_1 \setminus B_r$, $F : B_1 \rightarrow \mathbb{R}^{3 \times 3}$, $\operatorname{curl} F = b\delta_0$

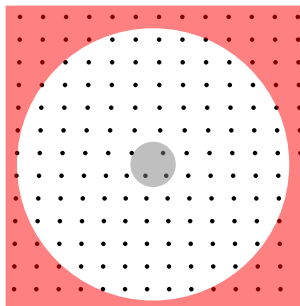


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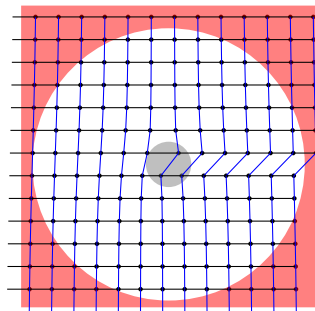


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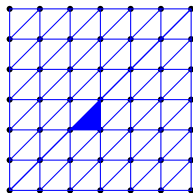
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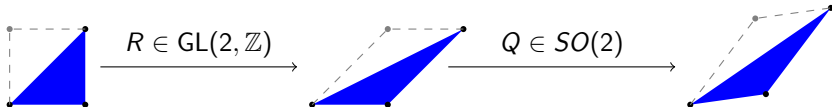
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Atomic-scale finite elements for reconstructive phase transformations



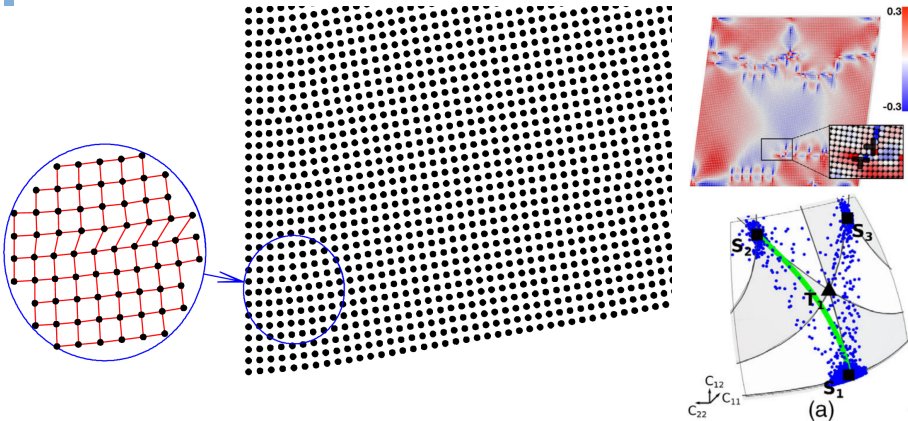
$$E = \sum_{t \in T} \min_{R \in GL(2, \mathbb{Z}), Q \in SO(2)} |\nabla u(t) - QR|^2$$



SC, Zanzotto ARMA 2004

Baggio, Arbib, Biscari, SC, Truskinovski, Zanzotto, Salman PRL 2019

Atomic-scale finite elements for reconstructive phase transformations



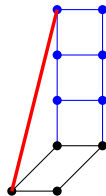
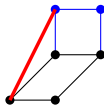
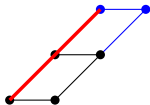
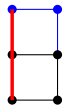
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Linearize!!

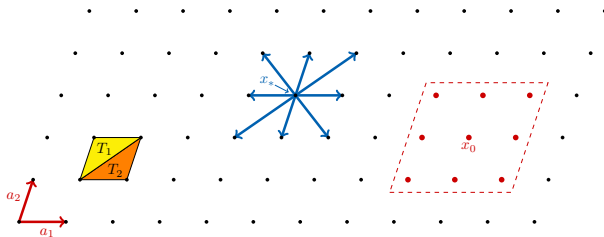
$$\varphi(x) = QFRx, \quad Q \in SO(2), \quad F \in GL^+(2, \mathbb{R}), \quad R \in GL(2, \mathbb{Z})$$

$$\begin{aligned} \varphi(x+h) - \varphi(x) &= QFRh = h + QF(R - Id)h + (QF - Id)h \\ &\simeq h + (R - Id)h + (QF - Id)h \\ &=: h + \xi^{pl}(x, h) + \xi^{el}(x, h) \end{aligned}$$



Basis: Ariza-Ortiz ARMA 2005, Related: Giuliani-Theil JEMS 2022

$\mathcal{L} = F\mathbb{Z}^n$ lattice, $\mathcal{N} \subset \mathcal{L}$ bonds, $\mathcal{C} \subset \mathcal{L}$ cluster



Elastic kinematics:

$$u : \Omega \cap \epsilon \mathcal{L} \rightarrow \mathbb{R}^n, \quad du(x, h) := \frac{u(x + \epsilon h) - u(x)}{\epsilon} \quad (x \in \Omega \cap \epsilon \mathcal{L}, h \in \mathcal{N})$$

$$\mathcal{C}_{\mathcal{N}} := \{(x, h) : x, x + h \in \mathcal{C}, h \in \mathcal{N}\}$$

$$\xi_{x_0}[u] : \mathcal{C}_{\mathcal{N}} \rightarrow \mathbb{R}^n, \quad \text{e.g., } \xi_{x_0}(y, h) := du(x_0 + \epsilon y, h)$$

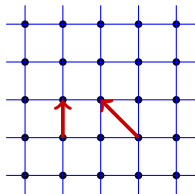
$$\text{Compatibility: } \xi(x, h) = -\xi(x + \epsilon h, -h)$$

Linear Ariza-Ortiz model

Ariza-Ortiz:

$$\sum_{x,y,h,h'} B_{x,y,h,h'} (\xi - \xi^{pl})(x, h)(\xi - \xi^{pl})(y, h')$$

Boundary conditions?



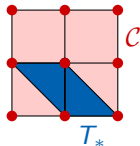
Giuliani-Theil:

$$\frac{1}{2} \sum_{x \sim y} [(u(y) - u(x) - \xi^{pl}(x, y - x)) \cdot (y - x)]^2, \quad \xi^{pl}(x, y - x) \in \mathcal{L}$$

Elastic energy

$E_C : D_C \rightarrow \mathbb{R}_{\geq 0}$, quadratic, $E_C[\xi] = E_C[\xi + F]$ for $F \in \mathbb{R}_{\text{skew}}^{n \times n}$

$$\alpha \min_F \sum_{(x,h) \in T_*} |\xi(x,h) - Fh|^2 \leq E_C[\xi]$$



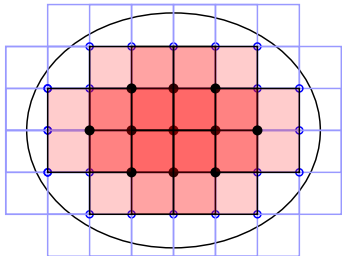
Example: $E_C^0[\xi] := \min_F \sum_{(x,h) \in \mathcal{C}_\mathcal{N}} |\xi(x,h) - Fh|^2$.

Elastic constants: $\frac{1}{2} \mathbb{C} A \cdot A := |T_*| E_C[A]$

Total energy: $E_\epsilon[u_\epsilon, \Omega] = \sum_{x+\epsilon \mathcal{C} \subset \Omega \cap \epsilon \mathcal{L}} \epsilon^3 E_C[\xi_x[u_\epsilon]]$

■ 2.

■ Elastic energy

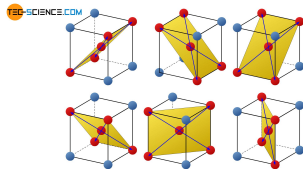


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Plastic slip

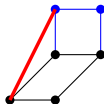
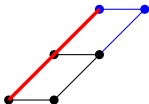
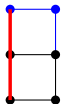
$$(b_1, m_1), \dots, (b_{N_s}, m_{N_s}) \in \mathcal{L} \times \mathcal{L}^*$$

Slip systems



$$\xi^{pl}(x, h) = \sum_{\ell=1}^{N_s} b_{\ell} \zeta_{\ell}(x, h) (m_{\ell} \cdot h), \quad \zeta_{\ell}(x, h) m_{\ell} \cdot h \in \mathbb{Z}$$

$$\xi = \xi^{el} + \xi^{pl}$$

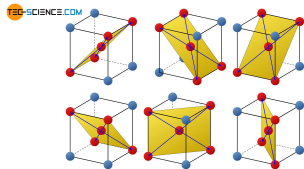


2.

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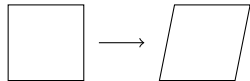
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$$F = \sum_{\ell} \gamma_{\ell} b_{\ell} \otimes m_{\ell} \quad Fh = \sum_{\ell} \gamma_{\ell} b_{\ell} (m_{\ell} \cdot h)$$

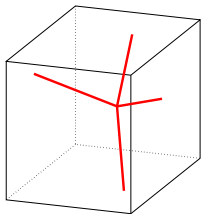


■ 3.

■ Dilute dislocations

■ $\gamma = \cup \gamma_i \subset \Omega$, γ_i segments, $|\gamma_i| \geq \alpha_\epsilon$,
 ■ similar bound for angles, $\alpha_\epsilon \rightarrow 0$ slowly.

■ ξ "curl-free" on $\Omega \setminus B_{\rho_\epsilon}(\gamma_\epsilon)$

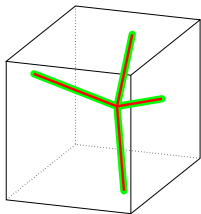


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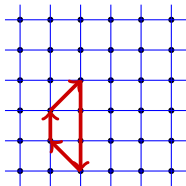
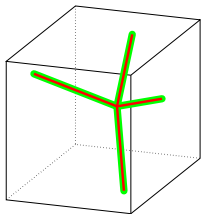


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$$\text{circ}(\xi, \{x_0, \dots, x_K = x_0\}) := \sum_i \xi(x_i, x_{i+1} - x_i)$$



Dilute dislocations

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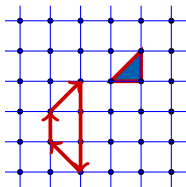
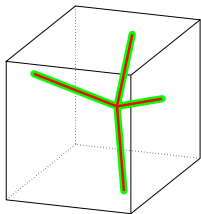
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$$\text{circ}(\xi, \{x_0, \dots, x_K = x_0\}) := \sum_i \xi(x_i, x_{i+1} - x_i)$$

t simplex, $\text{circ}(\xi, \cdot) = 0$ on t : $\xi(x, h) = F_t h$ on t .

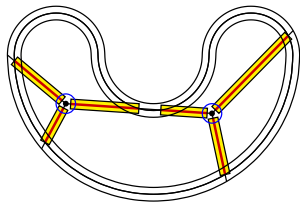
Interpolate:

$$(L\xi)(t) := \operatorname{argmin}_{F \in \mathbb{R}^{3 \times 3}} \sum_{(x, x+h) \in t} |Fh - \xi(x, h)|^2$$



Extension+rigidity

Extension: If $\text{circ} L\xi = 0$ in $\Omega \setminus B_\rho(\cup_i \gamma_i)$,
 $\exists$ extension $\beta \in L^1(\Omega'; \mathbb{R}^{3 \times 3})$
 with $\text{curl } \beta = \sum_i \theta_i \otimes t_i \mathcal{H}^1 \llcorner \gamma_i \cap \Omega'$,
 $\|\beta\|_{3/2} \leq \|L\xi\|_{3/2}$.



Theorem [SC-Garroni 2021]:

For any $\beta \in L^1(\Omega; \mathbb{R}^{n \times n})$ there is $R \in \mathbb{R}_{\text{skw}}^{n \times n}$ such that

$$\|\beta - R\|_{L^{1^*}} \leq C \|\beta + \beta^T\|_{L^{1^*}} + C |\text{curl } \beta|(\Omega)$$

+ the corresponding nonlinear estimate, with $1^* = n/(n-1)$

$n = 2$, linear: Garroni-Leoni-Ponsiglione 2010

$n = 2$, nonlinear: Müller-Scardia-Zeppieri 2014

■ Γ convergence

■ Let $E_\epsilon : X_\epsilon \rightarrow [0, \infty]$, $E_0 : X_0 \rightarrow [0, \infty]$.

■ Fix a convergence criterion $x_\epsilon \rightarrow x_0$ ($x_\epsilon \in X_\epsilon$, $x_0 \in X_0$).

■ $E_\epsilon \xrightarrow{\Gamma} E_0$ iff:

a) $E_0[x_0] \leq \liminf E_\epsilon[x_\epsilon]$ for all sequences $x_\epsilon \rightarrow x_0$;

b) $\forall x_0, \exists x_\epsilon \rightarrow x_0$ with $E_0[x_0] \geq \limsup E_\epsilon[x_\epsilon]$.

Compactness: If $\sup_\epsilon E_\epsilon[x_\epsilon] < \infty$, then there is a convergent subsequence.

Here: $\xi_\epsilon \rightarrow \beta$ if the interpolations converge weakly in L^p

3. Discrete-to-continuum, elasticity

Theorem [SC-Garroni-Ortiz 2022]: $E_\epsilon[u_\epsilon, \Omega] \xrightarrow{\Gamma} \int_\Omega \frac{1}{2} \mathbb{C} Du \cdot Du dx.$

Key estimate: $E_\epsilon[\psi_\delta * u_\epsilon, \omega'] \leq E_\epsilon[u_\epsilon, B_\delta(\omega')]$

$$\int_{\omega'} \frac{1}{2} \mathbb{C} F_\delta \cdot F_\delta dx \leq (1 + c \frac{\epsilon}{\delta}) E_\epsilon[u_\epsilon, \omega], \text{ where } F_\delta := \psi_\delta * DJ_\epsilon u_\epsilon$$

Continuum-to-continuum, dilute dislocations

$$E_\epsilon^c = \int_{\Omega \setminus B_\epsilon(\gamma_\epsilon)} \frac{1}{2} \mathbb{C} \beta \cdot \beta, \quad \operatorname{curl} \beta = \epsilon b \otimes t \mathcal{H}^1 \llcorner \gamma$$

Theorem [SC-Garroni-Ortiz 2015, SC-Garroni-Marziani 2022]

If γ_ϵ dilute,

$$\frac{1}{\epsilon^2 \ln \frac{1}{\epsilon}} E_\epsilon^c[\beta_\epsilon] \xrightarrow{\Gamma} E_0[\eta, \mu] := \int_{\Omega} \frac{1}{2} \mathbb{C} \eta \cdot \eta dx + \int_{\gamma} \psi_{\mathbb{C}}^{\text{rel}}(b, t) d\mathcal{H}^1$$

Topology:

- $\beta_\epsilon \rightarrow S$ in L^1 , $S \in \mathbb{R}_{\text{skw}}^{3 \times 3}$
- $\mu_\epsilon := \frac{1}{\epsilon} \operatorname{curl} \beta_\epsilon \rightharpoonup \mu = b \otimes t \mathcal{H}^1 \llcorner \gamma$
- $\frac{\beta_\epsilon - S_\epsilon}{\epsilon \ln^{1/2} \frac{1}{\epsilon}} \rightharpoonup \eta$ in $L^{\frac{3}{2}}$; $\operatorname{curl} \eta = 0$

Discrete-to-continuum, dilute dislocations

Theorem [SC-Garroni-Ortiz 2023+]

If γ_ϵ dilute and ξ_ϵ curl-free on $\Omega \setminus B_{m\epsilon}(\gamma_\epsilon)$,

$$\frac{1}{\epsilon^2 \ln \frac{1}{\epsilon}} E_\epsilon[\xi_\epsilon] \xrightarrow{\Gamma} E_0[\eta, \mu] = \int_\Omega \frac{1}{2} \mathbb{C} \eta \cdot \eta + \int_\gamma \psi_{\mathbb{C}}^{rel}(b, t) d\mathcal{H}^1$$

Topology:

$$\frac{1}{\epsilon} \operatorname{curl} L \xi_\epsilon \rightharpoonup \mu = b \otimes t \mathcal{H}^1 \llcorner \gamma \text{ in } \mathcal{D}'$$

$$\frac{L \xi_\epsilon - S_\epsilon}{\epsilon \ln^{1/2} \epsilon} \chi_{\Omega \setminus B_{m\epsilon}(\gamma_\epsilon)} \rightharpoonup \eta \text{ in } L_{loc}^{3/2}$$

3. Discrete-to-continuum, dilute dislocations

Theorem [SC-Garroni-Ortiz 2023+]

If γ_ϵ dilute and ξ_ϵ curl-free on $\Omega \setminus B_{m\epsilon}(\gamma_\epsilon)$,

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Topology:

$$\frac{1}{\epsilon} \operatorname{curl} L \xi_\epsilon \rightharpoonup \mu = b \otimes t \mathcal{H}^1 \llcorner \gamma \text{ in } \mathcal{D}'$$

$$\left[\frac{1}{\epsilon} \int_\Omega L \xi_\epsilon \cdot \operatorname{curl} \varphi dx \rightarrow \int_\gamma b \varphi \cdot t d\mathcal{H}^1 \quad \forall \varphi \in C_c^\infty(\Omega; \mathbb{R}^3) \right]$$

$$\frac{L \xi_\epsilon - S_\epsilon}{\epsilon \ln^{1/2} \epsilon} \chi_{\Omega \setminus B_{m\epsilon}(\gamma_\epsilon)} \rightharpoonup \eta \text{ in } L_{loc}^{3/2}$$

■ Straight dislocations: from $\mathbb{C}$ to $\psi_{\mathbb{C}}$

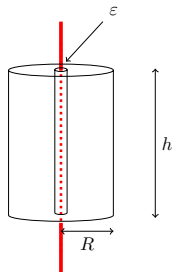
Theorem [SC-Garroni-Ortiz 2015]:

$$\lim_{h \rightarrow \infty} \lim_{\epsilon \rightarrow 0} \frac{1}{h \ln(R/\epsilon)} \inf \int_{T_{\epsilon,R}^h} \frac{1}{2} \mathbb{C} \beta \cdot \beta = \psi_{\mathbb{C}}(b, t)$$

with $\text{curl } \beta = b \otimes t \mathcal{H}^1 \llcorner (\mathbb{R}t)$,

$$T_{\epsilon,R}^h = (B_R \setminus B_{\epsilon}) \times (0, h),$$

$\psi_{\mathbb{C}}(b, t)$ the energy of the 1d solution



Straight dislocations: from $\mathbb{C}$ to $\psi_{\mathbb{C}}$

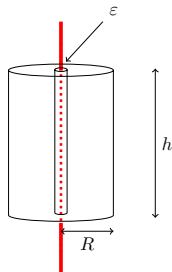
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$\psi_{\mathbb{C}}(b, t)$ the energy of the 1d solution



Proof strategy:

Uniform Korn's inequality

Average in direction t , reduce to 2D

Again Korn, affine inside and outside

Uniqueness of the solution to $\text{div } \mathbb{C} \beta = 0$, $\text{curl } \beta = \mu$