

# Geometry of interaction and non-determinism

Marco Pedicini (Roma Tre University)  
joint work with Mario Piazza, SNS Pisa

XXVIII Incontro di Logica AILA

Udine, 3-6 settembre 2024

# Outline

- actions of streams

# Outline

- actions of streams
- lambda calculus and choice as syntactic sugar

# Outline

- actions of streams
- lambda calculus and choice as syntactic sugar
- Lamping and the PELCR-VM

# Outline

- actions of streams
- lambda calculus and choice as syntactic sugar
- Lamping and the PELCR-VM
- molecular dynamics vs local and asynchronous computations

# Outline

- actions of streams
- lambda calculus and choice as syntactic sugar
- Lamping and the PELCR-VM
- molecular dynamics vs local and asynchronous computations
- execution formula and its dynamics, non-determinism and solution *à la Gillespie*

# Outline

- actions of streams
- lambda calculus and choice as syntactic sugar
- Lamping and the PELCR-VM
- molecular dynamics vs local and asynchronous computations
- execution formula and its dynamics, non-determinism and solution *à la Gillespie*

# STREAMS & MACHINES

# Streams and Actions

A **stream**  $(\alpha_j)_j$  is a sequence of **actions**  $\alpha_j$  of a given set  $A$ .

# Streams and Actions

A **stream**  $(\alpha_j)_j$  is a sequence of **actions**  $\alpha_j$  of a given set  $A$ .

**Stream processing** machines, which inspire real world parallel computing devices like GPU's, take a stream and compute by processing action by action.

# Streams and Actions

A **stream**  $(\alpha_j)_j$  is a sequence of **actions**  $\alpha_j$  of a given set  $A$ .

**Stream processing** machines, which inspire real world parallel computing devices like GPU's, take a stream and compute by processing action by action.

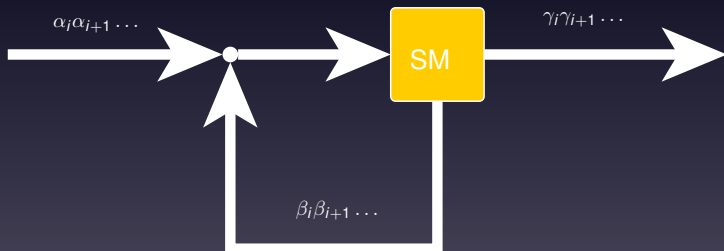


# Streams and Actions

A **stream**  $(\alpha_j)_j$  is a sequence of **actions**  $\alpha_j$  of a given set  $A$ .

**Stream processing** machines, which inspire real world parallel computing devices like GPU's, take a stream and compute by processing action by action.

When an action is processed possibly many new actions are generated, feeding the stream.



# Streams and Actions

A **stream**  $(\alpha_j)_j$  is a sequence of **actions**  $\alpha_j$  of a given set  $A$ .

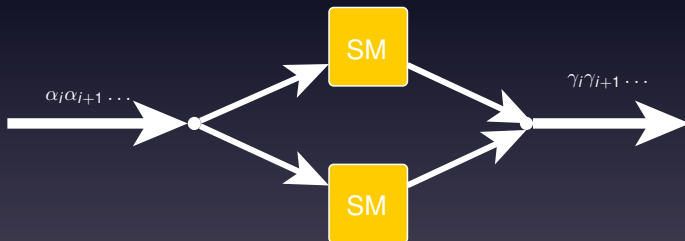
**Stream processing** machines, which inspire real world parallel computing devices like GPU's, take a stream and compute by processing action by action.



# Streams and Actions

A **stream**  $(\alpha_j)_j$  is a sequence of **actions**  $\alpha_j$  of a given set  $A$ .

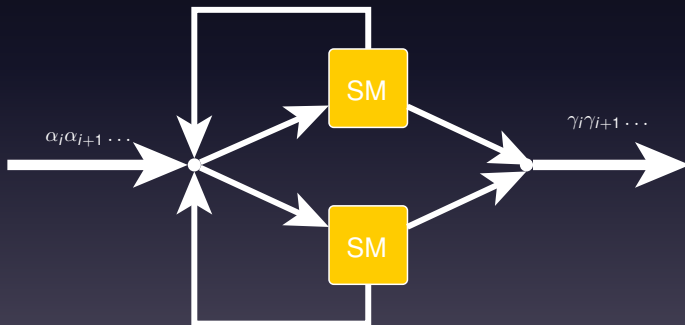
**Stream processing** machines, which inspire real world parallel computing devices like GPU's, take a stream and compute by processing action by action.



# Streams and Actions

A **stream**  $(\alpha_j)_j$  is a sequence of **actions**  $\alpha_j$  of a given set  $A$ .

**Stream processing** machines, which inspire real world parallel computing devices like GPU's, take a stream and compute by processing action by action.



# PELCR-VM

The **PELCR-VM** defined in Lai et al., 2019, follows implementations in Pedicini, 1998; Pedicini e Quaglia, 2000, 2007, it is a **stream based abstract machine** where actions comes from the **Geometry of Interaction** interpretation of proof-nets (MELL fragment) and evaluation mimics optimal reduction of  $\lambda$ -calculus Asperti e Chroboczek, 1997; Gonthier et al., 1992; Lévy, 1978, 1980.

# PELCR-VM

The **PELCR-VM** defined in Lai et al., 2019, follows implementations in Pedicini, 1998; Pedicini e Quaglia, 2000, 2007, it is a **stream based abstract machine** where actions comes from the **Geometry of Interaction** interpretation of proof-nets (MELL fragment) and evaluation mimics optimal reduction of  $\lambda$ -calculus Asperti e Chroboczek, 1997; Gonthier et al., 1992; Lévy, 1978, 1980.

$S$  : (stack) current action(s)

# PELCR-VM

The **PELCR-VM** defined in Lai et al., 2019, follows implementations in Pedicini, 1998; Pedicini e Quaglia, 2000, 2007, it is a **stream based abstract machine** where actions comes from the **Geometry of Interaction** interpretation of proof-nets (MELL fragment) and evaluation mimics optimal reduction of  $\lambda$ -calculus Asperti e Chroboczek, 1997; Gonthier et al., 1992; Lévy, 1978, 1980.

$S$  : (stack) current action(s)

$E$  : (environment) part of the configuration required to execute an action

# PELCR-VM

The **PELCR-VM** defined in Lai et al., 2019, follows implementations in Pedicini, 1998; Pedicini e Quaglia, 2000, 2007, it is a **stream based abstract machine** where actions comes from the **Geometry of Interaction** interpretation of proof-nets (MELL fragment) and evaluation mimics optimal reduction of  $\lambda$ -calculus Asperti e Chroboczek, 1997; Gonthier et al., 1992; Lévy, 1978, 1980.

$S$  : (stack) current action(s)

$E$  : (environment) part of the configuration required to execute an action

$C$  : (core) stream of actions to be processed

# PELCR-VM

The **PELCR-VM** defined in Lai et al., 2019, follows implementations in Pedicini, 1998; Pedicini e Quaglia, 2000, 2007, it is a **stream based abstract machine** where actions comes from the **Geometry of Interaction** interpretation of proof-nets (MELL fragment) and evaluation mimics optimal reduction of  $\lambda$ -calculus Asperti e Chroboczek, 1997; Gonthier et al., 1992; Lévy, 1978, 1980.

*S* : (stack) current action(s)

*E* : (environment) part of the configuration required to execute an action

*C* : (core) stream of actions to be processed

*D* : (dump) configuration containing all environments

# PELCR-VM

The **PELCR-VM** defined in Lai et al., 2019, follows implementations in Pedicini, 1998; Pedicini e Quaglia, 2000, 2007, it is a **stream based abstract machine** where actions comes from the **Geometry of Interaction** interpretation of proof-nets (MELL fragment) and evaluation mimics optimal reduction of  $\lambda$ -calculus Asperti e Chroboczek, 1997; Gonthier et al., 1992; Lévy, 1978, 1980.

$S$  : (stack) current action(s)

$E$  : (environment) part of the configuration required to execute an action

$C$  : (core) stream of actions to be processed

$D$  : (dump) configuration containing all environments

$(S, E, C, D)$

# PELCR-VM

The **PELCR-VM** defined in Lai et al., 2019, follows implementations in Pedicini, 1998; Pedicini e Quaglia, 2000, 2007, it is a **stream based abstract machine** where actions comes from the **Geometry of Interaction** interpretation of proof-nets (MELL fragment) and evaluation mimics optimal reduction of  $\lambda$ -calculus Asperti e Chroboczek, 1997; Gonthier et al., 1992; Lévy, 1978, 1980.

$$\text{POP} \frac{(\langle \rangle, \text{NULL}, \alpha :: C, D)}{(\alpha, \text{NULL}, C, D)}$$

get the next action from the stream

# PELCR-VM

The **PELCR-VM** defined in Lai et al., 2019, follows implementations in Pedicini, 1998; Pedicini e Quaglia, 2000, 2007, it is a **stream based abstract machine** where actions comes from the **Geometry of Interaction** interpretation of proof-nets (MELL fragment) and evaluation mimics optimal reduction of  $\lambda$ -calculus Asperti e Chroboczek, 1997; Gonthier et al., 1992; Lévy, 1978, 1980.

$$\text{POP} \frac{(\langle \rangle, \text{NULL}, \alpha :: C, D)}{(\alpha, \text{NULL}, C, D)}$$

get the next action from the stream

$$\text{ENV} \frac{(\langle \alpha \rangle, \text{NULL}, C, D) \quad \alpha \neq \mathbf{0}}{(\langle \alpha \rangle, \text{target}(\alpha), C, D \cup \{\text{target}(\alpha)\})}$$

prepare the environment

# PELCR-VM

The **PELCR-VM** defined in Lai et al., 2019, follows implementations in Pedicini, 1998; Pedicini e Quaglia, 2000, 2007, it is a **stream based abstract machine** where actions comes from the **Geometry of Interaction** interpretation of proof-nets (MELL fragment) and evaluation mimics optimal reduction of  $\lambda$ -calculus Asperti e Chroboczek, 1997; Gonthier et al., 1992; Lévy, 1978, 1980.

$$\text{POP} \frac{(\langle \rangle, \text{NULL}, \alpha :: C, D)}{(\alpha, \text{NULL}, C, D)}$$

get the next action from the stream

$$\text{ENV} \frac{(\langle \alpha \rangle, \text{NULL}, C, D) \quad \alpha \neq \mathbf{0}}{(\langle \alpha \rangle, \text{target}(\alpha), C, D \cup \{\text{target}(\alpha)\})}$$

prepare the environment

$$\text{HC} \frac{(\langle \alpha \rangle, \text{target}(\alpha), C, D)}{(\langle \rangle, \text{NULL}, C \times \text{execute}(\alpha), D \cup \{\alpha\})}$$

perform evaluation and merge in the stream new actions

# PELCR-VM

The **PELCR-VM** defined in Lai et al., 2019, follows implementations in Pedicini, 1998; Pedicini e Quaglia, 2000, 2007, it is a **stream based abstract machine** where actions comes from the **Geometry of Interaction** interpretation of proof-nets (MELL fragment) and evaluation mimics optimal reduction of  $\lambda$ -calculus Asperti e Chroboczek, 1997; Gonthier et al., 1992; Lévy, 1978, 1980.

$$\text{POP} \frac{(\langle \rangle, \text{NULL}, \alpha :: C, D)}{(\alpha, \text{NULL}, C, D)}$$

get the next action from the stream

$$\text{ENV} \frac{(\langle \alpha \rangle, \text{NULL}, C, D) \quad \alpha \neq \mathbf{0}}{(\langle \alpha \rangle, \text{target}(\alpha), C, D \cup \{\text{target}(\alpha)\})}$$

prepare the environment

$$\text{HC} \frac{(\langle \alpha \rangle, \text{target}(\alpha), C, D)}{(\langle \rangle, \text{NULL}, C \times \text{execute}(\alpha), D \cup \{\alpha\})}$$

perform evaluation and merge in the stream new actions

$$\text{NENV} \frac{(\langle \alpha \rangle, \text{NULL}, C, D) \quad \alpha = \mathbf{0}}{(\langle \rangle, \text{NULL}, C, D)}$$

idle cycle (if  $\alpha$  is the zero action)

# Back and forth

**Actions are paths** with a source node, a target node and the weight taken in the geometry of interaction **polarised Girard's Dynamic Algebra**.

# Back and forth

**Actions are paths** with a source node, a target node and the weight taken in the geometry of interaction **polarised Girard's Dynamic Algebra**.

**Execution of an action**  $\alpha$  to be performed within a context

$$\{\beta_1, \dots, \beta_n\}$$

generates new actions in pairs:

$$\alpha_i := \langle (\varepsilon_i, \varepsilon), (v_i, v'_i), a'_i \rangle \quad \text{and} \quad \beta'_i := \langle (\varepsilon_s, -\varepsilon), (v_s, v'_i), b'_i \rangle,$$

where  $\varepsilon$  is arbitrarily chosen in  $\{+, -\}$  and  $v'_i$  is a newly generated node and if  $b_i^* a \neq 0$ ,  $a'_i b_i^*$  is the stable form of  $b_i^* a$ .

# Back and forth

**Actions are paths** with a source node, a target node and the weight taken in the geometry of interaction **polarised Girard's Dynamic Algebra**.

**Execution of an action**  $\alpha$  to be performed within a context

$$\{\beta_1, \dots, \beta_n\}$$

generates new actions in pairs:

$$\alpha_i := \langle (\varepsilon_i, \varepsilon), (v_i, v'_i), a'_i \rangle \quad \text{and} \quad \beta'_i := \langle (\varepsilon_s, -\varepsilon), (v_s, v'_i), b'_i \rangle,$$

where  $\varepsilon$  is arbitrarily chosen in  $\{+, -\}$  and  $v'_i$  is a newly generated node and if  $b_i^* a \neq 0$ ,  $a'_i b_i^*$  is the stable form of  $b_i^* a$ .

Essentially an action is a **polarised edge in a weighted graph**:

$$\langle (\varepsilon_t, \varepsilon_s), (v_t, v_s), w \rangle,$$

and tracks the logical structure of a path in the proof-net.

# Parallel Evaluation

This setting was studied in Pedicini, 1998, and linked to **parallel evaluation** of optimal lambda calculus reduction.

# Parallel Evaluation

This setting was studied in Pedicini, 1998, and linked to **parallel evaluation** of optimal lambda calculus reduction.

Extensions with syntactical sugar (integers, or generic FFI) in parallel evaluation setting were also introduced: Cosentino et al., 2006; Mackie, 1995; Pedicini e Quaglia, 2002; Pinto, 2001.

# Parallel Evaluation

This setting was studied in Pedicini, 1998, and linked to **parallel evaluation** of optimal lambda calculus reduction.

Extensions with syntactical sugar (integers, or generic FFI) in parallel evaluation setting were also introduced: Cosentino et al., 2006; Mackie, 1995; Pedicini e Quaglia, 2002; Pinto, 2001.

In Pedicini e Piazza, 2024, we consider optimal reduction in the setting of **non-deterministic  $\lambda$ -calculus**:

# Parallel Evaluation

This setting was studied in Pedicini, 1998, and linked to **parallel evaluation** of optimal lambda calculus reduction.

Extensions with syntactical sugar (integers, or generic FFI) in parallel evaluation setting where also introduced: Cosentino et al., 2006; Mackie, 1995; Pedicini e Quaglia, 2002; Pinto, 2001.

In Pedicini e Piazza, 2024, we consider optimal reduction in the setting of **non-deterministic  $\lambda$ -calculus**:

$$x$$

if and only if  $t, u \in \Lambda_{\oplus}$  and  $x \in V$  a numerable set of *variables*.

# Parallel Evaluation

This setting was studied in Pedicini, 1998, and linked to **parallel evaluation** of optimal lambda calculus reduction.

Extensions with syntactical sugar (integers, or generic FFI) in parallel evaluation setting where also introduced: Cosentino et al., 2006; Mackie, 1995; Pedicini e Quaglia, 2002; Pinto, 2001.

In Pedicini e Piazza, 2024, we consider optimal reduction in the setting of **non-deterministic  $\lambda$ -calculus**:

$$x \quad (t)u$$

if and only if  $t, u \in \Lambda_{\oplus}$  and  $x \in V$  a numerable set of *variables*.

# Parallel Evaluation

This setting was studied in Pedicini, 1998, and linked to **parallel evaluation** of optimal lambda calculus reduction.

Extensions with syntactical sugar (integers, or generic FFI) in parallel evaluation setting where also introduced: Cosentino et al., 2006; Mackie, 1995; Pedicini e Quaglia, 2002; Pinto, 2001.

In Pedicini e Piazza, 2024, we consider optimal reduction in the setting of **non-deterministic  $\lambda$ -calculus**:

$$x \quad (t)u \quad \lambda xt$$

if and only if  $t, u \in \Lambda_{\oplus}$  and  $x \in V$  a numerable set of *variables*.

# Parallel Evaluation

This setting was studied in Pedicini, 1998, and linked to **parallel evaluation** of optimal lambda calculus reduction.

Extensions with syntactical sugar (integers, or generic FFI) in parallel evaluation setting where also introduced: Cosentino et al., 2006; Mackie, 1995; Pedicini e Quaglia, 2002; Pinto, 2001.

In Pedicini e Piazza, 2024, we consider optimal reduction in the setting of **non-deterministic  $\lambda$ -calculus**:

$$x \quad (t)u \quad \lambda xt \quad [t \oplus u]$$

if and only if  $t, u \in \Lambda_{\oplus}$  and  $x \in V$  a numerable set of *variables*.

# Parallel Evaluation

This setting was studied in Pedicini, 1998, and linked to **parallel evaluation** of optimal lambda calculus reduction.

Extensions with syntactical sugar (integers, or generic FFI) in parallel evaluation setting where also introduced: Cosentino et al., 2006; Mackie, 1995; Pedicini e Quaglia, 2002; Pinto, 2001.

In Pedicini e Piazza, 2024, we consider optimal reduction in the setting of **non-deterministic  $\lambda$ -calculus**:

$$x \quad (t)u \quad \lambda xt \quad [t \oplus u]$$

# Parallel Evaluation

This setting was studied in Pedicini, 1998, and linked to **parallel evaluation** of optimal lambda calculus reduction.

Extensions with syntactical sugar (integers, or generic FFI) in parallel evaluation setting where also introduced: Cosentino et al., 2006; Mackie, 1995; Pedicini e Quaglia, 2002; Pinto, 2001.

In Pedicini e Piazza, 2024, we consider optimal reduction in the setting of **non-deterministic  $\lambda$ -calculus**:

$$x \quad (t)u \quad \lambda xt \quad [t \oplus u]$$

if and only if  $t, u \in \Lambda_{\oplus}$  and  $x \in V$  a numerable set of *variables*.

# Sharing Graphs

A new **sound and lazy** operational interpretation of non-determinism is defined (**choice-by-need**) and we show to be compatible with shared reduction:

$$(\lambda xt)u \rightarrow_{\beta} t[u/x]$$

# Sharing Graphs

A new **sound and lazy** operational interpretation of non-determinism is defined (**choice-by-need**) and we show to be compatible with shared reduction:

$$(\lambda xt)u \rightarrow_{\beta} t[u/x] \quad ([t \oplus u])v \rightarrow_{\oplus} [(t)v \oplus (u)v]$$

# Sharing Graphs

A new **sound and lazy** operational interpretation of non-determinism is defined (**choice-by-need**) and we show to be compatible with shared reduction:

$$(\lambda xt)u \rightarrow_{\beta} t[u/x] \quad ([t \oplus u])v \rightarrow_{\oplus} [(t)v \oplus (u)v]$$

**Shared graphs:**



axiom



cut



variable



root



application



abstraction



sharing



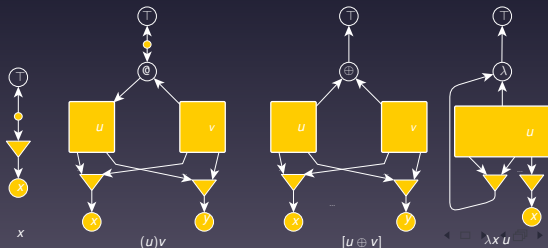
choice

# Sharing Graphs

A new **sound and lazy** operational interpretation of non-determinism is defined (**choice-by-need**) and we show to be compatible with shared reduction:

$$(\lambda xt)u \rightarrow_{\beta} t[u/x] \quad ([t \oplus u])v \rightarrow_{\oplus} [(t)v \oplus (u)v]$$

**Shared graphs:**



# Reduction Rules



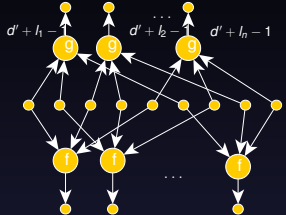
$\Rightarrow$



(a) annihilation



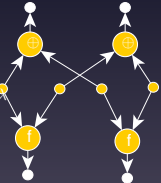
$(d < d') \Rightarrow$



(b) commutation

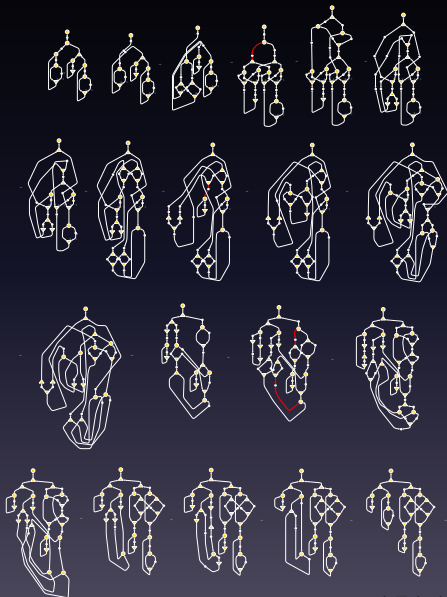


$\Rightarrow$   
with  $f = @$  or  $f = \times$



(c) commutation of choice

# Example of Reduction



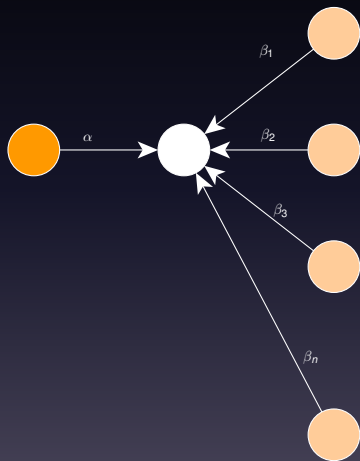
# Local and Asynchronous

One only type of **active configuration**.



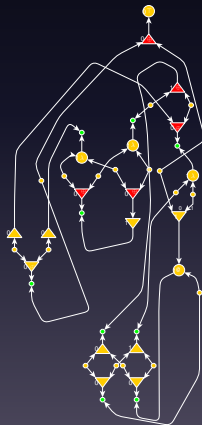
# Local and Asynchronous

One only type of **active configuration**. Active configurations can be **executed concurrently** without affecting the result.



# Local and Asynchronous

One only type of **active configuration**. Active configurations can be **executed concurrently** without affecting the result. Actions can be viewed as interacting particles: there is a collision at the **target node**, with the **context**.



# Local and Asynchronous

One only type of **active configuration**. Active configurations can be **executed concurrently** without affecting the result. Actions can be viewed as interacting particles: there is a collision at the **target node**, with the **context**. In parallel evaluation this permits to naturally **distribute active configurations** on available units.

# Local and Asynchronous

One only type of **active configuration**. Active configurations can be **executed concurrently** without affecting the result. Actions can be viewed as interacting particles: there is a collision at the **target node**, with the **context**. In parallel evaluation this permits to naturally **distribute active configurations** on available units.

**Choice operator** is a syntactic element establishing two separate possible **evolutions in the execution**.

# Local and Asynchronous

One only type of **active configuration**. Active configurations can be **executed concurrently** without affecting the result. Actions can be viewed as interacting particles: there is a collision at the **target node**, with the **context**. In parallel evaluation this permits to naturally **distribute active configurations** on available units.

**Choice operator** is a syntactic element establishing two separate possible **evolutions in the execution**. As a consequence of nesting of the choice operator, possible evolutions should be **differentially prioritized** while executed, giving rise to a **quantitative operational semantics**.

# Local and Asynchronous

One only type of **active configuration**. Active configurations can be **executed concurrently** without affecting the result. Actions can be viewed as interacting particles: there is a collision at the **target node**, with the **context**. In parallel evaluation this permits to naturally **distribute active configurations** on available units.

**Choice operator** is a syntactic element establishing two separate possible **evolutions in the execution**. As a consequence of nesting of the choice operator, possible evolutions should be **differentially prioritized** while executed, giving rise to a **quantitative operational semantics**.

# MOLECULES

# Stochastic Semantics

Example of quantitative semantics for Petri Nets, Stochastic Pi-Calculus and Gene expression evolution.

# Stochastic Semantics

Example of quantitative semantics for Petri Nets, Stochastic Pi-Calculus and Gene expression evolution.

Reaction Rules with reaction constants: rules with occurrence probabilities.

# Stochastic Semantics

Example of quantitative semantics for Petri Nets, Stochastic Pi-Calculus and Gene expression evolution.

Reaction Rules with reaction constants: rules with occurrence probabilities.

Simulation which correctly takes in account probabilities.

# Stochastic Semantics

Example of quantitative semantics for Petri Nets, Stochastic Pi-Calculus and Gene expression evolution.

Reaction Rules with reaction constants: rules with occurrence probabilities.

Simulation which correctly takes in account probabilities.

How to compute them ?

# Gillespie's Algorithm

The Gillespie algorithm is a stochastic simulation method used to simulate the time evolution of a set of coupled chemical reactions within a reacting system.

- 1 **Initialization:** Set the initial number of molecules for each species, time  $t = 0$ .

# Gillespie's Algorithm

The Gillespie algorithm is a stochastic simulation method used to simulate the time evolution of a set of coupled chemical reactions within a reacting system.

- 1 **Initialization:** Set the initial number of molecules for each species, time  $t = 0$ .
- 2 **Calculate Propensities:** For each reaction  $j$ , calculate the propensity function  $a_j = c_j \cdot h_j(X)$  where  $c_j$  is the rate constant and  $h_j(X)$  is the number of possible combinations of reactant molecules.

# Gillespie's Algorithm

The Gillespie algorithm is a stochastic simulation method used to simulate the time evolution of a set of coupled chemical reactions within a reacting system.

- 1 **Initialization:** Set the initial number of molecules for each species, time  $t = 0$ .
- 2 **Calculate Propensities:** For each reaction  $j$ , calculate the propensity function  $a_j = c_j \cdot h_j(X)$  where  $c_j$  is the rate constant and  $h_j(X)$  is the number of possible combinations of reactant molecules.
- 3 **Total Propensity:** Compute the total propensity  $a_0 = \sum_j a_j$ .

# Gillespie's Algorithm

The Gillespie algorithm is a stochastic simulation method used to simulate the time evolution of a set of coupled chemical reactions within a reacting system.

- 1 **Initialization:** Set the initial number of molecules for each species, time  $t = 0$ .
- 2 **Calculate Propensities:** For each reaction  $j$ , calculate the propensity function  $a_j = c_j \cdot h_j(X)$  where  $c_j$  is the rate constant and  $h_j(X)$  is the number of possible combinations of reactant molecules.
- 3 **Total Propensity:** Compute the total propensity  $a_0 = \sum_j a_j$ .
- 4 **Generate Random Numbers:** Generate two random numbers  $r_1, r_2 \in [0, 1]$ .

# Gillespie's Algorithm

The Gillespie algorithm is a stochastic simulation method used to simulate the time evolution of a set of coupled chemical reactions within a reacting system.

- 1 **Initialization:** Set the initial number of molecules for each species, time  $t = 0$ .
- 2 **Calculate Propensities:** For each reaction  $j$ , calculate the propensity function  $a_j = c_j \cdot h_j(X)$  where  $c_j$  is the rate constant and  $h_j(X)$  is the number of possible combinations of reactant molecules.
- 3 **Total Propensity:** Compute the total propensity  $a_0 = \sum_j a_j$ .
- 4 **Generate Random Numbers:** Generate two random numbers  $r_1, r_2 \in [0, 1]$ .
- 5 **Time to Next Reaction:** Calculate the time to the next reaction  $\tau = \frac{1}{a_0} \ln \frac{1}{r_1}$ .

# Gillespie's Algorithm

The Gillespie algorithm is a stochastic simulation method used to simulate the time evolution of a set of coupled chemical reactions within a reacting system.

- 1 **Initialization:** Set the initial number of molecules for each species, time  $t = 0$ .
- 2 **Calculate Propensities:** For each reaction  $j$ , calculate the propensity function  $a_j = c_j \cdot h_j(X)$  where  $c_j$  is the rate constant and  $h_j(X)$  is the number of possible combinations of reactant molecules.
- 3 **Total Propensity:** Compute the total propensity  $a_0 = \sum_j a_j$ .
- 4 **Generate Random Numbers:** Generate two random numbers  $r_1, r_2 \in [0, 1]$ .
- 5 **Time to Next Reaction:** Calculate the time to the next reaction  $\tau = \frac{1}{a_0} \ln \frac{1}{r_1}$ .
- 6 **Determine Reaction Rule:** Find reaction  $j$  such that  $\sum_{k=1}^{j-1} a_k < r_2 a_0 \leq \sum_{k=1}^j a_k$ .

# Gillespie's Algorithm

The Gillespie algorithm is a stochastic simulation method used to simulate the time evolution of a set of coupled chemical reactions within a reacting system.

- 1 **Initialization:** Set the initial number of molecules for each species, time  $t = 0$ .
- 2 **Calculate Propensities:** For each reaction  $j$ , calculate the propensity function  $a_j = c_j \cdot h_j(X)$  where  $c_j$  is the rate constant and  $h_j(X)$  is the number of possible combinations of reactant molecules.
- 3 **Total Propensity:** Compute the total propensity  $a_0 = \sum_j a_j$ .
- 4 **Generate Random Numbers:** Generate two random numbers  $r_1, r_2 \in [0, 1]$ .
- 5 **Time to Next Reaction:** Calculate the time to the next reaction  $\tau = \frac{1}{a_0} \ln \frac{1}{r_1}$ .
- 6 **Determine Reaction Rule:** Find reaction  $j$  such that  $\sum_{k=1}^{j-1} a_k < r_2 a_0 \leq \sum_{k=1}^j a_k$ .
- 7 **Update:** Update the system state by executing reaction  $j$ . Update time  $t = t + \tau$ .

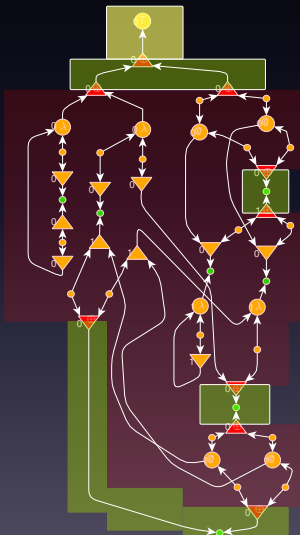
# Gillespie's Algorithm

The Gillespie algorithm is a stochastic simulation method used to simulate the time evolution of a set of coupled chemical reactions within a reacting system.

- 1 **Initialization:** Set the initial number of molecules for each species, time  $t = 0$ .
- 2 **Calculate Propensities:** For each reaction  $j$ , calculate the propensity function  $a_j = c_j \cdot h_j(X)$  where  $c_j$  is the rate constant and  $h_j(X)$  is the number of possible combinations of reactant molecules.
- 3 **Total Propensity:** Compute the total propensity  $a_0 = \sum_j a_j$ .
- 4 **Generate Random Numbers:** Generate two random numbers  $r_1, r_2 \in [0, 1]$ .
- 5 **Time to Next Reaction:** Calculate the time to the next reaction  $\tau = \frac{1}{a_0} \ln \frac{1}{r_1}$ .
- 6 **Determine Reaction Rule:** Find reaction  $j$  such that  $\sum_{k=1}^{j-1} a_k < r_2 a_0 \leq \sum_{k=1}^j a_k$ .
- 7 **Update:** Update the system state by executing reaction  $j$ . Update time  $t = t + \tau$ .
- 8 **Repeat:** Repeat steps 2-7 until the desired simulation time is reached.

# Probabilistic Geometry of Interaction

**Open Question** any action has a choice nesting depth (in the sharing graph).



- we give an interpretation of the choice nesting depth  $d$  as the rate  $c_d = 2^{-d}$ ,
- we count the total number of active configurations at any depth  $d$ :  $h(d)$
- then we apply Gillespie algorithm to schedule the current action  $a_d = c_d h(d)$  and normalise against the total propensity  $a = \sum_i a_i$ .

# Concluding remarks

- We introduced **sharing graphs** as a novel representation for the **non-deterministic lambda calculus**.
- The sharing graphs were interpreted within the framework of the **geometry of interactions** (GoI), providing a new perspective on the computational processes involved.
- We demonstrated that this interpretation can be effectively **evaluated using the PELCR-VM**, a virtual machine designed for efficient computation in this setting.
- This work opens new avenues for **further investigations** into the **operational nature of non-determinism** in computational systems.
- Future research could explore optimizing the evaluation strategies and understanding the implications of non-deterministic behaviors in broader computational contexts.

**THANKS!**

# REFERENCES



Asperti, A., & Chroboczek, J. (1997). Safe Operators: Brackets Closed Forever Optimizing Optimal Lambda-Calculus Implementations.. *Applicable Algebra in Engineering, Communication and Computing*, 8(6), 437–468.  
<http://dx.doi.org/10.1007/s002000050083>



Cosentino, A., Pedicini, M., & Quaglia, F. (2006). Supporting Function Calls within PELCR [Proceedings of the First International Workshop on Developments in Computational Models (DCM 2005)]. *Electronic Notes in Theoretical Computer Science*, 135(3), 107–117. <https://doi.org/https://doi.org/10.1016/j.entcs.2005.09.025>



Gonthier, G., Abadi, M., & Lévy, J.-J. (1992). The Geometry of Optimal Lambda Reduction. *Conference Record of the Nineteenth Annual ACM SIGPLAN-SIGACT Symposium on Principles of Programming Languages*, 15–26.  
[citeseer.ist.psu.edu/gonthier92geometry.html](http://citeseer.ist.psu.edu/gonthier92geometry.html)



Lai, A. C., Pedicini, M., & Piazza, M. (2019). Abstract machines, optimal reduction, and streams. *Mathematical*



Lévy, J.-J. (1978). *Réductions correctes et optimales dans le lambda-calcul* [Tesi di dottorato].



Lévy, J.-J. (1980). Optimal reductions in the lambda-calculus. *To HB Curry: Essays on Combinatory Logic, Lambda Calculus and Formalism*, 159–191.



Mackie, I. (1995). The geometry of interaction machine. *Proceedings of the 22nd ACM SIGPLAN-SIGACT Symposium on Principles of Programming Languages*, 198–208.



Pedicini, M. (1998). *Exécution et Programmes* [Tesi di dottorato, Université Paris VII].



Pedicini, M., & Piazza, M. (2024, giugno). *Optimal Reduction For Non-Deterministic Lambda Calculus*.



Pedicini, M., & Quaglia, F. (2000). A parallel implementation for optimal lambda-calculus reduction. *Proceedings of the 2nd ACM SIGPLAN international conference on*



Pedicini, M., & Quaglia, F. (2002). **Scheduling vs Communication in PELCR.** In B. Monien & R. Feldmann (Cur.), *Euro-Par 2002 Parallel Processing* (pp. 648–655). Springer Berlin Heidelberg.



Pedicini, M., & Quaglia, F. (2007). **PELCR: parallel environment for optimal lambda-calculus reduction.** *ACM Transactions on Computational Logic (TOCL)*, 8(3). <https://doi.org/10.1145/1243996.1243997>



Pinto, J. S. (2001). **Parallel Implementation Models for the Lambda-Calculus Using the Geometry of Interaction.** In *Typed Lambda Calculi and Applications (Abramsky, S., editor)* (pp. 385–399, Vol. 2044). Springer.